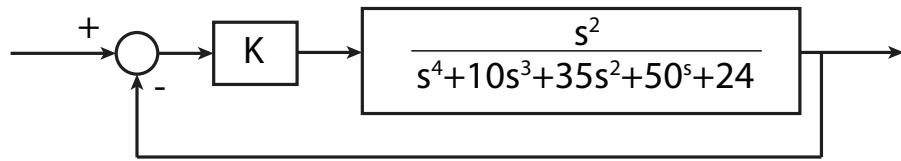


# 16.06 Principles of Automatic Control

## Recitation 3

### Routh Array



### Part 1.

For the feedback system above, find the values of  $K$  that make system stable/unstable.

For unstable system. determine # of RHP poles.

$$H(s) = \frac{Ks^2}{s^4 + 10s^3 + (35 + K)s^2 + 50s + 24}$$

Routh Array:

$$\begin{array}{cccc}
 s^4 & 1 & 35 + K & 24 \\
 s^3 & 10 & 50 & 0 \\
 s^2 & 30 + K & 24 & 0 \\
 s^1 & \frac{1260 + 50K}{K+30} & 0 & 0 \\
 s^0 & 24 & 0 & 0
 \end{array}$$

In order for the system to be stable, we need all elements in the first column to be positive, but the elements in the first column will change depending on  $K$ . Start by finding critical values for  $K$ :

$$K + 30 > 0 \rightarrow K > -30$$

$$\frac{1260+50K}{30+K} > 0 \rightarrow K > -25.2$$

Now consider the sign on the first elements of the first column for different ranges of  $K$ :

$K < -30$	$-25.2 < K < -30$	$K > -25.2$
+	+	+
+	+	+
-	+	+
+	-	+
+	+	+
2 sign changes	2 sign changes	no sign changes
2 RHP poles	2 RHP poles	no RHP poles
unstable	unstable	stable

## Part 2.

$$s^3 - 3s + 2$$

Routh array:

$$\begin{array}{cc} s^3 : & 1 \quad -3 \\ s^2 : & 0 \quad 2 \\ s & \\ 1 & \end{array}$$

Here, in the second row, we have a “0” in the first column. Since we can’t divide by “0”, we replace that entry by a small constant  $\epsilon$  and proceed.

$$\begin{array}{cccccc} s^3 : & 1 & -3 & \epsilon > 0 & \epsilon < 0 \\ s^2 : & \epsilon & 2 & + & + \\ s : & -3 - 2/\epsilon & 0 & \rightarrow & + & - \\ & 2 & 0 & & - & + \\ & & & & + & + \end{array} \rightarrow 2 \text{ sign changes} \rightarrow 2 \text{ RHP poles}$$

One can factor the polynomial and check:

$$s^3 - 3s + 2 = (s - 1)^2(s + 2) \rightarrow \text{poles at } s = 1, 1, -2.$$

Indeed, we have 2 RHP poles.

## Part 3.

$$s^5 + 2s^4 + 24s^3 + 48s^2 - 25s - 50$$

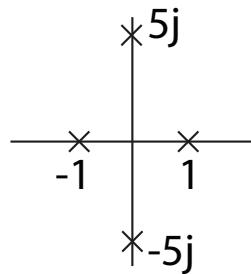
$$\begin{array}{l}
s^5 : \quad 1 \quad 24 \quad -25 \quad + \\
s^4 : \quad 2 \quad 48 \quad -50 \quad + \\
s^3 : \quad 0 \quad 0 \quad 0 \quad + \\
s^3 : \quad 8 \quad 96 \quad 0 \quad \rightarrow \quad + \quad \rightarrow \text{ One sign change} \quad \rightarrow 1 \text{ RHP pole.} \\
s^2 : \quad 24 \quad -50 \quad + \\
s : \quad 112.7 \quad 0 \quad + \\
1 : \quad -50 \quad - \\
\end{array}$$

For row 3, we get the entire row of zeros. Take previous characteristic equation ( $s^4$ ): auxiliary poles.

$P(s) = 2s^4 + 48s^2 - 50$ , differentiate this:

$\frac{\partial P}{\partial s} = 8s^3 + 96s$ . We use this results' coefficients in the  $s^3$  row.

Roots of auxiliary polynomial are shown below:



$$s^2 = 1 \rightarrow s = \pm 1$$

$$s^2 = 25 \rightarrow s = \pm 5j$$

MIT OpenCourseWare  
<http://ocw.mit.edu>

## 16.06 Principles of Automatic Control

Fall 2012

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.