SEARCHING AND SORTING ALGORITHMS

(download slides and .py files and follow along!)

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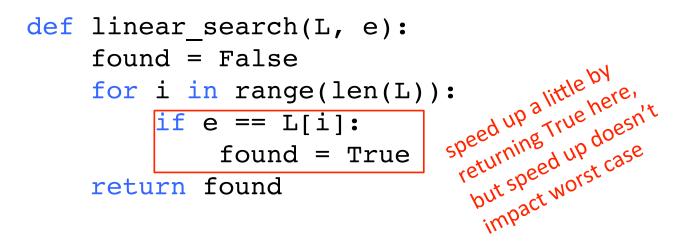
SEARCH ALGORITHMS

- search algorithm method for finding an item or group of items with specific properties within a collection of items
- collection could be implicit
 - example find square root as a search problem
 - exhaustive enumeration
 - bisection search
 - Newton-Raphson
- collection could be explicit
 - example is a student record in a stored collection of data?

SEARCHING ALGORITHMS

- linear search
 - brute force search (aka British Museum algorithm)
 - list does not have to be sorted
- bisection search
 - list MUST be sorted to give correct answer
 - saw two different implementations of the algorithm

LINEAR SEARCH ON UNSORTED LIST: RECAP



- must look through all elements to decide it's not there -Assumes we can
- O(len(L)) for the loop * O(1) to test if e == L[i]
- overall complexity is O(n) where n is len(L)

retrieve element

time

of list in constant

LINEAR SEARCH ON **SORTED** LIST: RECAP

```
def search(L, e):
    for i in range(len(L)):
        if L[i] == e:
            return True
        if L[i] > e:
            return False
    return False
```

- must only look until reach a number greater than e
- O(len(L)) for the loop * O(1) to test if e == L[i]
- overall complexity is O(n) where n is len(L)

USE BISECTION SEARCH: RECAP

- 1. Pick an index, i, that divides list in half
- 2. Ask if L[i] == e
- 3. If not, ask if L[i] is larger or smaller than e
- 4. Depending on answer, search left or right half of $\ L$ for e

A new version of a divide-and-conquer algorithm

- Break into smaller version of problem (smaller list), plus some simple operations
- Answer to smaller version is answer to original problem

BISECTION SEARCH IMPLEMENTATION: RECAP

```
def bisect search2(L, e):
    def bisect search helper(L, e, low, high):
        if high == low:
            return L[low] == e
        mid = (low + high)//2
        if L[mid] == e:
            return True
        elif L[mid] > e:
            if low == mid: #nothing left to search
                return False
            else:
                return bisect search helper(L, e, low, mid - 1)
        else:
            return bisect search helper(L, e, mid + 1, high)
    if len(L) == 0:
        return False
    else:
        return bisect search helper(L, e, 0, len(L) - 1)
```

COMPLEXITY OF BISECTION SEARCH: RECAP

bisect_search2 and its helper

- O(log n) bisection search calls
 - reduce size of problem by factor of 2 on each step
- pass list and indices as parameters
- list never copied, just re-passed as pointer
- constant work inside function
- \rightarrow O(log n)

SEARCHING A SORTED LIST -- n is len(L)

- using linear search, search for an element is O(n)
- using binary search, can search for an element in O(log n)
 - assumes the list is sorted!
- when does it make sense to sort first then search?
 - SORT + O(log n) < O(n) \rightarrow SORT < O(n) O(log n)
 - when sorting is less than O(n)
- NEVER TRUE!
 - to sort a collection of n elements must look at each one at least once!

AMORTIZED COST -- n is len(L)

- why bother sorting first?
- in some cases, may sort a list once then do many searches
- AMORTIZE cost of the sort over many searches
- **SORT +** K***O(**log n) < K***O(**n)

 \rightarrow for large K, **SORT time becomes irrelevant**, if cost of sorting is small enough

SORT ALGORITHMS

- Want to efficiently sort a list of entries (typically numbers)
- Will see a range of methods, including one that is quite efficient

MONKEY SORT

- aka bogosort, stupid sort, slowsort, permutation sort, shotgun sort
- to sort a deck of cards
 - throw them in the air
 - pick them up
 - are they sorted?
 - repeat if not sorted



COMPLEXITY OF BOGO SORT

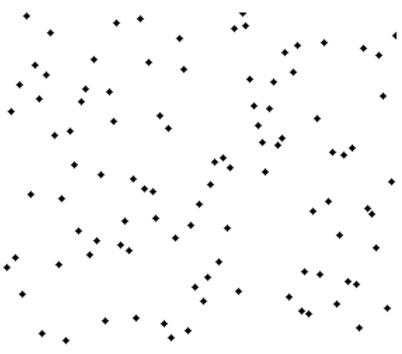
def bogo_sort(L):
 while not is_sorted(L):
 random.shuffle(L)

- best case: O(n) where n is len(L) to check if sorted
- worst case: O(?) it is unbounded if really unlucky

BUBBLE SORT

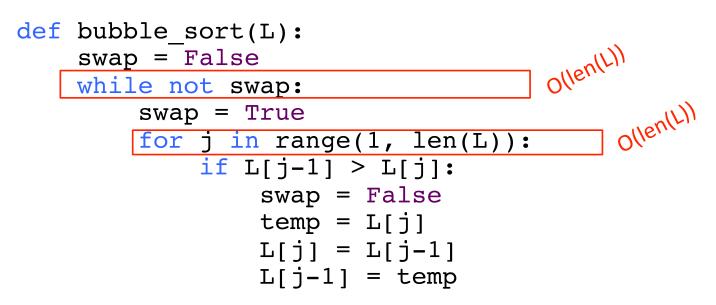
- compare consecutive pairs of elements
- swap elements in pair such that smaller is first
- when reach end of list, start over again
- stop when no more swaps have been made

 largest unsorted element always at end after pass, so at most n passes CC-BY Hydrargyrum https://commons.wikimedia.org/wiki/File:Bubble_sort_animation.gif



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COMPLEXITY OF BUBBLE SORT



- inner for loop is for doing the comparisons
- outer while loop is for doing multiple passes until no more swaps
- O(n²) where n is len(L) to do len(L)-1 comparisons and len(L)-1 passes

SELECTION SORT

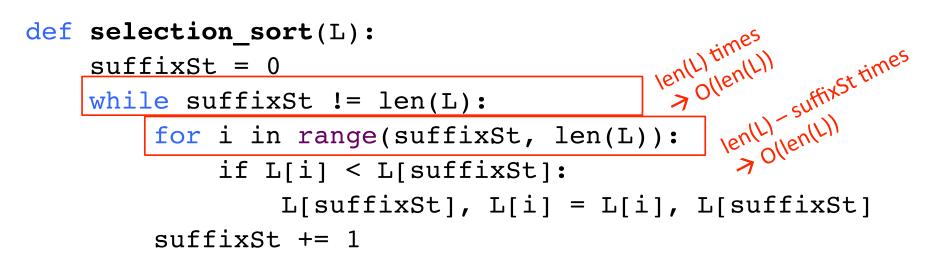
- first step
 - extract minimum element
 - swap it with element at index 0
- subsequent step
 - in remaining sublist, extract minimum element
 - swap it with the element at index 1
- keep the left portion of the list sorted
 - at i'th step, first i elements in list are sorted
 - all other elements are bigger than first i elements

ANALYZING SELECTION SORT

loop invariant

- given prefix of list L[0:i] and suffix L[i+1:len(L)], then prefix is sorted and no element in prefix is larger than smallest element in suffix
 - 1. base case: prefix empty, suffix whole list invariant true
 - induction step: move minimum element from suffix to end of prefix. Since invariant true before move, prefix sorted after append
 - 3. when exit, prefix is entire list, suffix empty, so sorted

COMPLEXITY OF SELECTION SORT

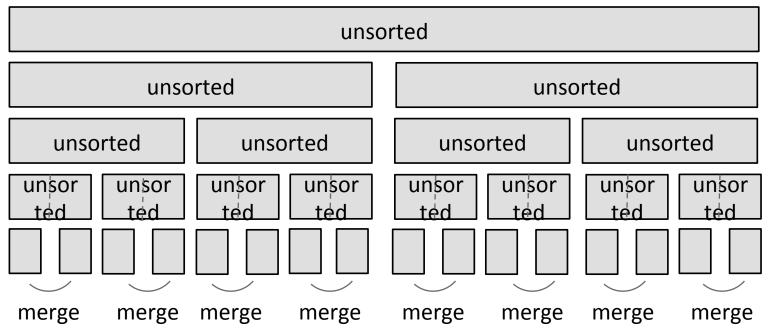


- outer loop executes len(L) times
- inner loop executes len(L) i times
- complexity of selection sort is O(n²) where n is len(L)

use a divide-and-conquer approach:

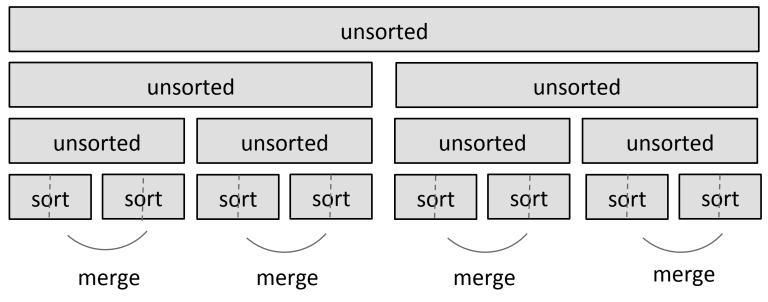
- 1. if list is of length 0 or 1, already sorted
- 2. if list has more than one element, split into two lists, and sort each
- 3. merge sorted sublists
 - 1. look at first element of each, move smaller to end of the result
 - 2. when one list empty, just copy rest of other list

divide and conquer



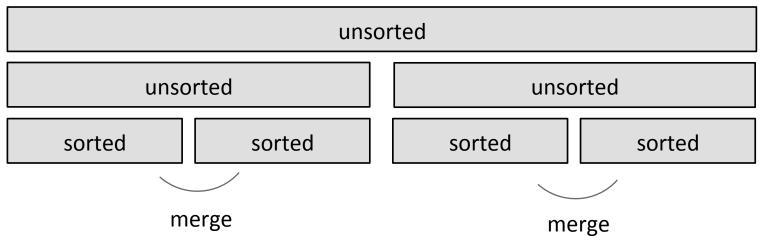
split list in half until have sublists of only 1 element

divide and conquer



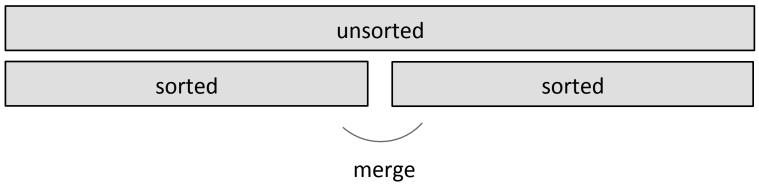
merge such that sublists will be sorted after merge

divide and conquer



- merge sorted sublists
- sublists will be sorted after merge

divide and conquer



- merge sorted sublists
- sublists will be sorted after merge

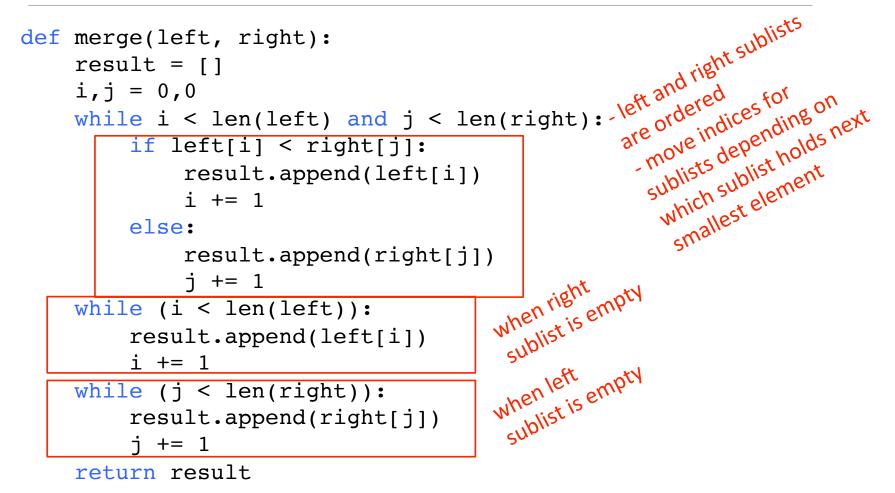
divide and conquer – done!

sorted

EXAMPLE OF MERGING

Left in list 1	Left in list 2	Compare	Result
[1]5,12,18,19,20]	23,4,17]	1-2	→①
[5]12,18,19,20]	(2)3,4,17]	5,2	— [⊉ ◯
(5) 12,18,19,20]	(3 4,17]	5,3	<u>[1,2]</u>
[5,12,18,19,20]	[4,17]	5, 4	[1,2,3]
[5,12,18,19,20]	[17]	5, 17	[1,2,3,4]
[12,18,19,20]	[17]	12, 17	[1,2,3,4,5]
[18,19,20]	[17]	18, 17	[1,2,3,4,5,12]
[18,19,20]	[]	18,	[1,2,3,4,5,12,17]
[]	[]		[1,2,3,4,5,12,17,18,19,20]

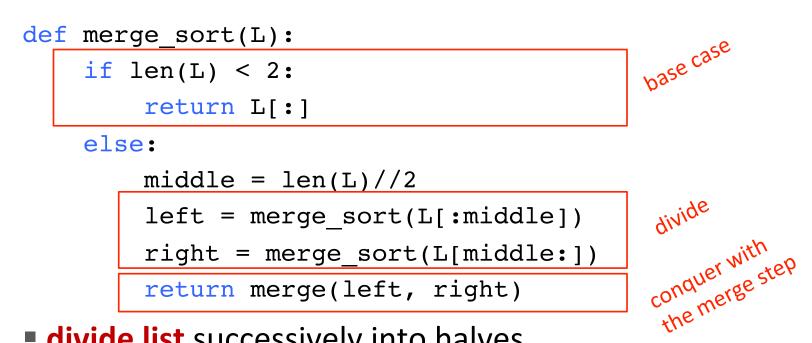
MERGING SUBLISTS STEP



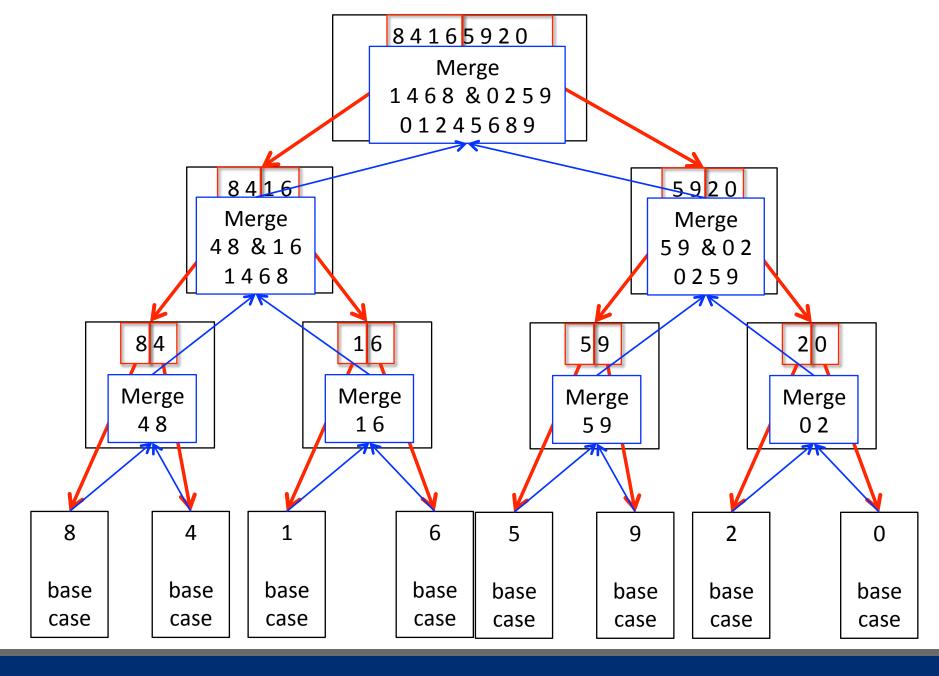
COMPLEXITY OF MERGING SUBLISTS STEP

- go through two lists, only one pass
- compare only smallest elements in each sublist
- O(len(left) + len(right)) copied elements
- O(len(longer list)) comparisons
- Inear in length of the lists

MERGE SORT ALGORITHM -- RECURSIVE



- divide list successively into halves
- depth-first such that conquer smallest pieces down one branch first before moving to larger pieces



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COMPLEXITY OF MERGE SORT

at first recursion level

- n/2 elements in each list
- O(n) + O(n) = O(n) where n is len(L)

at second recursion level

- n/4 elements in each list
- two merges \rightarrow O(n) where n is len(L)
- each recursion level is O(n) where n is len(L)
- dividing list in half with each recursive call
 O(log(n)) where n is len(L)
- overall complexity is O(n log(n)) where n is len(L)

SORTING SUMMARY -- n is len(L)

- bogo sort
 - randomness, unbounded O()
- bubble sort
 - O(n²)
- selection sort
 - O(n²)
 - guaranteed the first i elements were sorted
- merge sort
 - O(n log(n))
- O(n log(n)) is the fastest a sort can be

WHAT HAVE WE SEEN IN 6.0001?

KEY TOPICS

- represent knowledge with data structures
- iteration and recursion as computational metaphors
- abstraction of procedures and data types
- organize and modularize systems using object classes and methods
- different classes of algorithms, searching and sorting
- complexity of algorithms

OVERVIEW OF COURSE

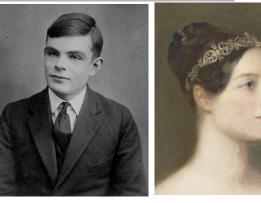
- Iearn computational modes of thinking
- - begin to master the art of computational problem solving
- make computers do what you want them to do

Hope we have started you down the path to being able to think and act like a computer scientist

WHAT DO COMPUTER SCIENTISTS DO?

- they think computationally
 - abstractions, algorithms, automated execution
- just like the three r's: reading,
 'riting, and 'rithmetic –
 computational thinking is
 becoming a fundamental skill that
 every well-educated person will
 need





Alan Turing

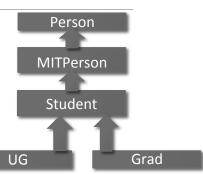
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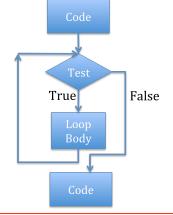


THE THREE A'S OF COMPUTATIONAL THINKING

- abstraction
 - choosing the right abstractions
 - operating in multiple layers of abstraction simultaneously
 - defining the relationships between the abstraction layers



- automation
 - think in terms of mechanizing our abstractions
 - mechanization is possible because we have precise and exacting notations and models; and because there is some "machine" that can interpret our notations
- algorithms
 - language for describing automated processes
 - also allows abstraction of details
 - language for communicating ideas & processes



def mergeSort(L, compare = operator.lt):
 if len(L) < 2:
 return L[:]
 else:
 middle = int(len(L)/2)
 left = mergeSort(L[:middle], compare)
 right = mergeSort(L[middle:], compare)</pre>

return merge(left, right, compare)

ASPECTS OF COMPUTATIONAL THINKING

- how difficult is this problem and how best can I solve it?
 - theoretical computer science gives precise meaning to these and related questions and their answers
- thinking recursively
 - reformulating a seemingly difficult problem into one which we know how to solve
 - reduction, embedding, transformation, simulation

O(*log n*) ; *O*(*n*) ; $O(n \log n);$ $O(n^2); O(c^n)$

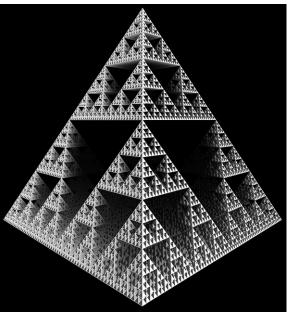


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