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Problem Set 5 - Solutions

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Problem 5.1**A**

$$\rho = \nabla \cdot \mathbf{D} = \nabla \cdot \epsilon \mathbf{E} = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z} \right) \cdot \epsilon E_0 (\hat{\mathbf{x}}x + \hat{\mathbf{y}}y) \sin \omega t = 2\epsilon E_0 \sin \omega t$$

$$-\frac{\partial}{\partial t} \mu \mathbf{H} = \nabla \times \mathbf{E} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \mathbf{0} \\ x & y & 0 \end{vmatrix} E_0 \sin \omega t = \hat{\mathbf{z}} \left(\frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} \right) E_0 \sin \omega t = 0$$

$$\Leftrightarrow \mathbf{H} = \mathbf{C}(\mathbf{r}) = \mathbf{0}$$

Time-independent magnetic field that could be set to zero, since it is not generated by the time dependent electric field.

$$\mathbf{J} = \nabla \times \mathbf{H} - \frac{\partial}{\partial t} \epsilon \mathbf{E} = \mathbf{0} - \frac{\partial}{\partial t} \epsilon E_0 (\hat{\mathbf{x}}x + \hat{\mathbf{y}}y) \sin \omega t = -\omega \epsilon E_0 (\hat{\mathbf{x}}x + \hat{\mathbf{y}}y) \cos \omega t$$

B

$$\rho = \nabla \cdot \epsilon \mathbf{E} = \left(\hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z} \right) \cdot \epsilon E_0 (\hat{\mathbf{x}}y - \hat{\mathbf{y}}x) \cos \omega t = \left(\frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} \right) \epsilon E_0 \cos \omega t = 0$$

$$-\frac{\partial}{\partial t} \mu \mathbf{H} = \nabla \times \mathbf{E} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \mathbf{0} \\ y & -x & 0 \end{vmatrix} E_0 \cos \omega t = \hat{\mathbf{z}} (-2E_0 \cos \omega t)$$

$$\Leftrightarrow \mathbf{H} = \hat{\mathbf{z}} \frac{2E_0}{\mu \omega} \sin \omega t + \mathbf{C}(\mathbf{r}) = \hat{\mathbf{z}} \frac{2E_0}{\omega \mu} \sin \omega t$$

$$\mathbf{J} = \nabla \times \mathbf{H} - \frac{\partial}{\partial t} \epsilon \mathbf{E} = \mathbf{0} - [-\omega \epsilon E_0 (\hat{\mathbf{x}}y - \hat{\mathbf{y}}x) \sin \omega t] = \omega \epsilon E_0 (\hat{\mathbf{x}}y - \hat{\mathbf{y}}x) \sin \omega t,$$

where the first term is $\mathbf{0}$ because \mathbf{H} does not depend on position.

Problem 5.2**A**

$$\omega = 4\pi \cdot 10^6 \frac{\text{rad}}{\text{sec}} \implies f = \frac{\omega}{2\pi} = 2 \cdot 10^6 \text{ Hz} = 2 \text{ MHz}$$

$$k = 4\pi \cdot 10^{-2} \frac{1}{\text{m}} \implies \lambda = \frac{2\pi}{k} = \frac{1}{2} \cdot 10^2 \text{ m} = 50 \text{ m}$$

$$c_n = \frac{\omega}{k} = \frac{4\pi \cdot 10^6}{4\pi \cdot 10^{-2}} \frac{\text{m}}{\text{sec}} = 10^8 \frac{\text{m}}{\text{sec}}$$

B

$$c_n = \frac{c}{n} \Leftrightarrow n = \frac{c}{c_n} = \frac{3 \cdot 10^8 \frac{\text{m}}{\text{sec}}}{10^8 \frac{\text{m}}{\text{sec}}} = 3$$

$$n = \sqrt{\varepsilon_r \mu_r} = \sqrt{\varepsilon_r \cdot 1} \Leftrightarrow \varepsilon_r = n^2 = 9$$

$$\eta = \sqrt{\frac{\mu}{\varepsilon}} = \sqrt{\frac{\mu_r \mu_0}{\varepsilon_r \varepsilon_0}} = \sqrt{\frac{\mu_r}{\varepsilon_r}} \sqrt{\frac{\mu_0}{\varepsilon_0}} = \sqrt{\frac{1}{9}} \cdot 120\pi \Omega = \frac{1}{3} \cdot 120\pi \Omega = 40\pi \Omega$$

Note: $\begin{cases} n = \text{index of refraction} \\ \eta = \text{impedance} \end{cases}$

$$-\frac{\partial}{\partial t} \mu_0 \mathbf{H} = \nabla \times \mathbf{E} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ 0 & 0 & \frac{\partial}{\partial z} \\ E_x & 0 & 0 \end{vmatrix} = +\hat{\mathbf{y}} \frac{\partial E_x}{\partial z} = \hat{\mathbf{y}} \frac{\partial}{\partial z} E_0 \cos(\omega t - kz)$$

$$\Rightarrow -\frac{\partial}{\partial t} \mu_0 \mathbf{H} = \hat{\mathbf{y}} E_0 k \sin(\omega t - kz) \Rightarrow \mathbf{H} = \hat{\mathbf{y}} \frac{E_0 k}{\omega \mu_0} \cos(\omega t - kz) + \mathbf{C}(r)^0$$

$$\Rightarrow \mathbf{H} = \hat{\mathbf{y}} \frac{E_0}{c_n \mu_0} \cos(\omega t - kz) = \hat{\mathbf{y}} \frac{E_0}{\eta} \cos(\omega t - kz)$$

$$\Rightarrow \mathbf{H} = \hat{\mathbf{y}} \frac{1}{4\pi} \cos(4\pi \cdot 10^6 t - 4\pi \cdot 10^{-2} z) \text{ Ampères/m}$$

C

$$\mathbf{S} = \mathbf{E} \times \mathbf{H} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ E_x & E_y & E_z \\ H_x & H_y & H_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ E_x & 0 & 0 \\ 0 & H_y & 0 \end{vmatrix} = \hat{\mathbf{z}} E_x H_y$$

$$\Rightarrow \mathbf{S} = \hat{\mathbf{z}} E_0 \frac{E_0}{\eta} \cos^2(\omega t - kz) = \hat{\mathbf{z}} 10 \cdot \frac{1}{4\pi} \cos^2(4\pi \cdot 10^6 t - 4\pi \cdot 10^{-2} z) \frac{\text{W}}{\text{m}^2}$$

$$\Rightarrow \mathbf{S} = \hat{\mathbf{z}} \frac{2.5}{\pi} \cos^2(4\pi \cdot 10^6 t - 4\pi \cdot 10^{-2} z) \frac{\text{W}}{\text{m}^2}$$

Problem 5.3**A**

$$\frac{\partial}{\partial t} \mathbf{J} = \omega_p^2 \varepsilon \mathbf{E} \Rightarrow \frac{\partial}{\partial t} \text{Re}[\hat{\mathbf{J}} e^{j\omega t}] = \omega_p^2 \varepsilon \text{Re}[\hat{\mathbf{E}} e^{j\omega t}]$$

$$\Rightarrow \text{Re}[j\omega \hat{\mathbf{J}} e^{j\omega t}] = \text{Re}[\omega_p^2 \varepsilon \hat{\mathbf{E}} e^{j\omega t}] \Rightarrow j\omega \hat{\mathbf{J}} = \omega_p^2 \varepsilon \hat{\mathbf{E}}$$

$$\Rightarrow \sigma(\omega) = \frac{\hat{\mathbf{J}}}{\hat{\mathbf{E}}} = \frac{\omega_p^2 \varepsilon}{j\omega} = -j\varepsilon \frac{\omega_p^2}{\omega}$$

B

$$j\omega \varepsilon(\omega) \hat{\mathbf{E}} = \hat{\mathbf{J}} + j\omega \varepsilon \hat{\mathbf{E}} = \sigma(\omega) \hat{\mathbf{E}} + j\omega \varepsilon \hat{\mathbf{E}} \Rightarrow j\omega \varepsilon(\omega) = \sigma(\omega) + j\omega \varepsilon$$

$$j\omega \varepsilon(\omega) = -j\varepsilon \frac{\omega_p^2}{\omega} + j\omega \varepsilon \Rightarrow \varepsilon(\omega) = \varepsilon \left(1 - \frac{\omega_p^2}{\omega^2} \right)$$

C

$$k = \omega \sqrt{\varepsilon(\omega) \mu_0} \implies$$

- $k_0 = \omega \sqrt{\varepsilon_0 \mu_0}$

- $k_p = \omega \sqrt{\varepsilon \left(1 - \frac{\omega_p^2}{\omega^2}\right) \mu_0} = \omega \sqrt{\varepsilon \mu_0} \sqrt{1 - \frac{\omega_p^2}{\omega^2}} = \begin{cases} \omega \sqrt{\varepsilon \mu_0} \sqrt{1 - \frac{\omega_p^2}{\omega^2}}, & \omega \geq \omega_p \\ j\omega \sqrt{\varepsilon \mu_0} \sqrt{\frac{\omega_p^2}{\omega^2} - 1}, & \omega < \omega_p \end{cases}$

D

$$\nabla \times \hat{\mathbf{E}} = -j\omega \mu_0 \hat{\mathbf{H}} \implies \hat{\mathbf{H}} = -\frac{1}{j\omega \mu_0} \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ 0 & 0 & \frac{\partial}{\partial z} \\ \hat{E}_x & 0 & 0 \end{vmatrix} = -\hat{\mathbf{y}} \frac{1}{j\omega \mu_0} \frac{\partial \hat{E}_x}{\partial z}$$

- $\hat{\mathbf{H}}_0 = -\hat{\mathbf{y}} \frac{j k_0}{j\omega \mu_0} \hat{E}_0 e^{jk_0 z} = -\hat{\mathbf{y}} \frac{k_0}{\omega \mu_0} \hat{E}_0 e^{jk_0 z}, z < 0$

- $\hat{\mathbf{H}}_0 = -\hat{\mathbf{y}} \frac{-jk_p}{j\omega \mu_0} \hat{E}_p e^{-jk_p z} = \hat{\mathbf{y}} \frac{k_p}{\omega \mu_0} \hat{E}_p e^{-jk_p z}, z > 0$

Note: The hat $\hat{\cdot}$ above x, y, z denotes a unit vector, but above field components denotes a complex phasor.

E

- $\hat{\mathbf{z}} \times (\hat{\mathbf{E}}_p - \hat{\mathbf{E}}_0) = \mathbf{0} \implies \hat{\mathbf{y}}(\hat{E}_p - \hat{E}_0) = \mathbf{0} \implies \hat{E}_p = \hat{E}_0 \equiv \hat{E}$
- $\hat{\mathbf{z}} \times (\hat{\mathbf{H}}_p - \hat{\mathbf{H}}_0) = \hat{\mathbf{K}} \implies -\hat{\mathbf{x}}(\hat{H}_p - \hat{H}_0) = K_0 \hat{\mathbf{x}} \implies \hat{H}_p - \hat{H}_0 = -K_0$

F

$$\hat{H}_0 - \hat{H}_p = K_0 \xrightarrow{\text{D,E}} -\frac{k_0}{\omega \mu_0} \hat{E} - \frac{k_p}{\omega \mu_0} \hat{E} = K_0 \implies \hat{E} = -\frac{\omega \mu_0}{k_0 + k_p} K_0$$

Therefore:

$$\hat{\mathbf{E}}(z) = \begin{cases} -\hat{\mathbf{x}} \frac{\omega \mu_0}{k_0 + k_p} K_0 e^{-jk_p z}, & z > 0 \\ -\hat{\mathbf{x}} \frac{\omega \mu_0}{k_0 + k_p} K_0 e^{jk_0 z}, & z < 0 \end{cases}$$

and

$$\hat{\mathbf{H}}(z) = \begin{cases} -\hat{\mathbf{y}} \frac{k_p}{k_0 + k_p} K_0 e^{-jk_p z}, & z > 0 \\ \hat{\mathbf{y}} \frac{k_0}{k_0 + k_p} K_0 e^{jk_0 z}, & z < 0 \end{cases}$$

G

In the field expressions above μ_0, ω, k_0, K_0 are real, therefore:

$$\langle \mathbf{S} \rangle = \frac{1}{2} \operatorname{Re}[\hat{\mathbf{E}} \times \hat{\mathbf{H}}^*] = \frac{1}{2} \operatorname{Re}[\hat{E}_x \hat{H}_y^*] \hat{\mathbf{z}} \implies$$

- $\langle \mathbf{S}_0 \rangle = -\hat{\mathbf{z}} \frac{1}{2} \operatorname{Re} \left[\frac{\omega \mu_0}{k_0 + k_p} K_0 e^{jk_0 z} \cdot \frac{k_0}{k_0 + k_p^*} K_0 e^{-jk_0 z} \right]$
 $= -\hat{\mathbf{z}} \frac{1}{2} \operatorname{Re} \left[\frac{\omega \mu_0 k_0}{|k_0 + k_p|^2} K_0^2 \right] = -\hat{\mathbf{z}} \frac{\omega \mu_0 k_0}{2|k_0 + k_p|^2} K_0^2$

$$\begin{aligned}
 \bullet \langle \mathbf{S}_p \rangle &= \hat{\mathbf{z}} \frac{1}{2} \operatorname{Re} \left[\frac{\omega \mu_0}{k_0 + k_p} K_0 e^{-jk_p z} \cdot \frac{k_p^*}{k_0 + k_p^*} K_0 e^{+jk_p^* z} \right] \\
 &= \hat{\mathbf{z}} \frac{1}{2} \operatorname{Re} \left[\frac{\omega \mu_0 k_p^*}{|k_0 + k_p|^2} K_0^2 e^{2\operatorname{Im}\{k_p\}z} \right] = \hat{\mathbf{z}} \frac{\omega \mu_0}{2|k_0 + k_p|^2} K_0^2 \operatorname{Re}\{k_p\} e^{2\operatorname{Im}\{k_p\}z} \\
 \implies \langle \hat{\mathbf{S}}_p \rangle &= \begin{cases} \hat{\mathbf{z}} \frac{\omega \mu_0}{2|k_0 + k_p|^2} K_0^2 \omega \sqrt{\varepsilon \mu_0} \sqrt{1 - \frac{\omega_p^2}{\omega^2}}, & \omega \geq \omega_p \\ 0, & \omega < \omega_p \text{ (because } \operatorname{Re}\{k_p\} = 0) \end{cases}
 \end{aligned}$$

When the wavevector is purely imaginary inside a medium, the fields decay exponentially (they are called “evanescent”) and no power is carried by them.

Problem 5.4

A

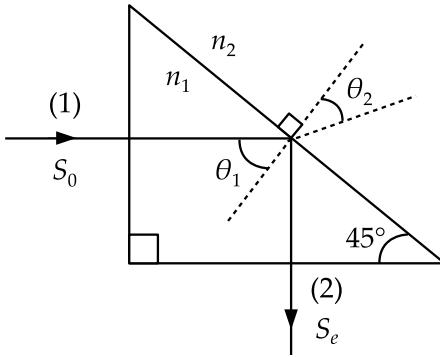


Figure 1: Diagram for Problem 5.4 Part A. (Image by MIT OpenCourseWare.)

For no power to be transmitted across the prism hypotenuse, the angle of incidence must be above the critical angle. In general, from Snell's Law:

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

and for total internal reflection:

$$\sin \theta_2 \geq 1 \implies \frac{n_1}{n_2} \sin \theta_1 \geq 1 \stackrel{\theta_1 = 45^\circ}{\implies} n_1 \geq n_2 \sqrt{2}$$

So for free space ($n_2 = 1$) : $n_{1,\min} = \sqrt{2} \approx 1.414$
and for water ($n_2 = 1.33$) : $n_{1,\min} = 1.33\sqrt{2} \approx 1.88$

B

The reflection coefficient at the input surface (1) is

$$r_{(1)} = \frac{n_1 - n_2}{n_1 + n_2} = r$$

and at the output surface (2) is

$$r_{(2)} = \frac{n_2 - n_1}{n_2 + n_1} = -r.$$

Therefore the reflectivity is

$$R = |r|^2 = \left| \frac{n_1 - n_2}{n_1 + n_2} \right|^2 = \left| \frac{\frac{n_1}{n_2} - 1}{\frac{n_1}{n_2} + 1} \right|^2.$$

For $n_1 \geq n_2\sqrt{2}$ no power is lost at the hypotenuse, so the power transmitted over the input is:

$$\begin{aligned} S_{(2)} = (1 - R)(1 - R)S_{(1)} &\implies \frac{S_{(2)}}{S_{(1)}} = (1 - R)^2 = \left[1 - \left(\frac{\frac{n_1}{n_2} - 1}{\frac{n_1}{n_2} + 1} \right)^2 \right]^2 \\ &\implies \frac{S_{(2)}}{S_{(1)}} = \left\{ \frac{\left[\left(\frac{n_1}{n_2} \right)^2 + 2\frac{n_1}{n_2} + 1 \right] - \left[\left(\frac{n_1}{n_2} \right)^2 - 2\frac{n_1}{n_2} + 1 \right]}{\left(\frac{n_1}{n_2} + 1 \right)^2} \right\}^2 = \left[\frac{4\frac{n_1}{n_2}}{\left(\frac{n_1}{n_2} + 1 \right)^2} \right]^2 \end{aligned}$$

For the values calculated in part A $n_1 = n_2\sqrt{2}$ for both cases, therefore:

$$\frac{S_{(2)}}{S_{(1)}} = \left[\frac{4\sqrt{2}}{(\sqrt{2} + 1)^2} \right]^2 \approx 0.943$$

for both cases.