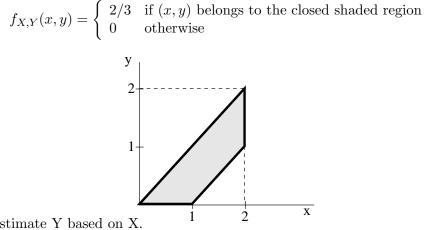
Tutorial 11

1. Continuous random variables X and Y have a joint PDF given by



We want to estimate Y based on X.

- (a) Find the LMS estimator g(X) of Y.
- (b) Calculate the conditional mean squared error $\mathbf{E}\left[(Y g(X))^2 \mid X = x\right]$.
- (c) Calculate the mean squared error $\mathbf{E}\left[(Y g(X))^2\right]$. Is it the same as $\mathbf{E}\left[\operatorname{var}(Y|X)\right]$?
- (d) Derive L(X), the linear LMS estimator of Y based on X.
- (e) How do you expect the mean squared error of L(X) to compare to that of g(X)?
- (f) What problem do you expect to encounter, if any, if you try to find the MAP estimator for Y based on observations of X.
- 2. Consider a noisy channel over which you send messages consisting of 0s and 1s to your friend. It is known that the channel independently flips each bit sent with some fixed probability p; however the value of p is unknown. You decide to conduct some experiments to estimate p and seek your friend's help. Your friend, cheeky as she is, insists that you send her messages consisting of three bits each (which you will both agree upon in advance); for each message, she will only tell you the total number of bits in that message that were flipped. Let X denote the number of bits flipped in a particular three-bit message.
 - (a) Find the PMF of X.
 - (b) Derive the ML estimator for p based on X_1, \ldots, X_n , the numbers of bits flipped in the first n three-bit messages.
 - (c) Is the ML estimator unbiased?
 - (d) Is the ML estimator consistent?
 - (e) You send n = 100 three-bit messages and find that the total number of bits flipped is 20. Construct a 95% confidence interval for p. If necessary, you may use a conservative bound on the variance of the number of bits flipped.
 - (f) What are some other ways to estimate the variance. How do you expect your confidence interval to change with different estimates of the variance.

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