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6.776 High Speed Communication Circuits Lecture 18 ABC's of Power Amplifiers

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Resistor Loaded Class A Amplifier

- In a Class A amplifier, the active device conducts current 100% of time
- For maximum output swing (and thus output power), the quiescent output voltage is set at V_{dd}/2, and bias current at V_{dd}/2R₁



Power Efficiency

Power Efficiency is defined as the ratio between power delivered to the load and the DC biasing power

Max. power delivered to load (R_L)

$$P_{L,max} = \frac{\left(\frac{V_{DD}}{2}\right)^2}{2R_L} = \frac{V_{DD}^2}{8R_L}$$

DC Biasing Power

$$P_{DC} = V_{DD} \cdot \frac{V_{DD}}{2R_L} = \frac{V_{DD}^2}{2R_L}$$

Max. Power Efficiency

$$\eta = \frac{P_L}{P_{DC}} = \frac{1}{4}$$

The efficiency is lower at smaller amplitudes (η is proportional to output power since DC power is constant)

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Other Power Efficiency Parameters

 Normalized Power Output Capability P_N Ratio between power delivered to load and peak current times peak voltage on the output device

Measure related to output device power handling

$$P_N = \frac{P_{L,max}}{v_{DS,max} \cdot i_{D,max}} = \frac{\frac{V_{DD}^2}{8R_L}}{V_{DD} \cdot \frac{V_{DD}}{R_L}} = \frac{1}{8}$$

Power Added Efficiency (PAE)
 Added signal power by the amplifier divided by DC biasing power

$$PAE = \frac{P_L - P_{in}}{P_{DC}}$$

At low frequencies, PAE= η for the previous amplifier

Class A RF Power Amplifier

Inductor improves peak amplitude, thus power efficiency



L₁: Large inductor: acts as current source C₁: DC block (prevents DC power in R_L) L₂, C₂: Output tank circuit

Drain Voltage and Current Waveforms

Since L₁ presents a DC short to V_{DD}, the drain voltage waveform must be symmetric around V_{DD}. the maximum amplitude of sinusoid at the drain is V_{DD}.



The drain voltage (and the output voltage) swings to twice the power supply! (in practice limited by device breakdown)

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$$i_D = I_{DC} + i_{rf} sinw_o t$$
$$v_{out} = -i_{rf} R_L sinw_o t$$

Since C₁ is effectively a short circuit at ω_o the amplitude of v_{out} is eval to the amplitude of v_{DS}:



Normalized Power Output Capability

$$P_{N} = \frac{P_{L,max}}{v_{DS,max} \cdot i_{D,max}}$$

$$P_{L,max} = \frac{V_{DD}^{2}}{2R_{L}}$$

$$v_{DS,max} = 2V_{DD} \qquad i_{D,max} = \frac{2V_{DD}}{R_{L}}$$

$$P_{N,max} = \frac{1}{8}$$

Class A amplifiers are linear, but have poor efficiency!

Class B Power Amplifier

Same circuit, but V_{bias} is set so that M1 conducts only 50% of time



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Class B Power Amplifier

V_{bias} is set so that M1 conducts only 50% of time



The harmonics in the output waveform are filtered by output tank circuit

The fundamental component is a linear function of the input

Class B Power Efficiency

The fundamental component of i_D half-sine wave is

$$i_{fund} = rac{2}{T} \int_0^{T/2} i_{rf}(sinw_o t)(sinw_o t) dt = rac{i_{rf}}{2}$$

The tank circuit filters harmonics – only the fundamental component is delivered to load:

$$v_{out} = -rac{i_{rf}}{2}R_L sinw_o t$$

As in Class A amplifier, the maximum amplitude of v_{out} is V_{DD} (since C₁ is an AC short):

$$P_{L,max} = rac{V_{DD}^2}{2R_L}$$
 and $i_{rf} \leq rac{2V_{DD}}{R_L}$

Class B Power Efficiency, Continued

The DC component of max. i_D half-sine wave is

 $\overline{i_D} = \frac{1}{T} \int_0^{T/2} \frac{2V_{DD}}{R_L} sinw_0 t dt = \frac{2V_{DD}}{\pi R_L}$ The DC power is then $P_{DC} = \frac{2V_{DD}^2}{\pi R_L}$ I_{op} $I_{\text{op$



Normalized Output Power Capability $v_{DS,max} = 2V_{DD} \quad i_{D,max} = i_{rf} \leq \frac{2V_{DD}}{R_L} \quad P_{L,max} = \frac{V_{DD}^2}{2R_L}$ $P_N = \frac{P_L}{v_{DS,max} \cdot i_{D,max}} = \frac{1}{8} \quad : \text{Same as Class A}$

Since DC power is proportional to the amplitude, η is proportional to square root of output power: slower degradation at lower power than class A

Conduction Angle vs. Class

Conduction Angle \u03c6 : 2\u03c6 is the portion of period during which the output transistor M1 conducts



2φ=2π: Class A π<2φ<2π: Class AB 2φ=π: Class B 0<2φ<π: Class C

(Class AB or C output cannot be a linear function of input)

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Push-Pull Amplifier

Depending on V_{bias} and V_{in} push-pull amplifier can be operated as Class A, B, AB, C, or D amplifier.



- Theoretically a Class B push-pull amplifier has low distortion comparable to class A because either half will be conducting at any time.
- Real Class B is not possible because devices do not have abrupt turn-on characteristic- most are Class AB

Voltage and Current Waveforms of Class B Push-Pull



Waveforms shown for maximum amplitude output

typically, 'crossover distortion' arises at the switching point of the two halves due to imprecise turn-on voltages

Crossover distortion is reduced by class AB operation

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Class C Amplifier

Same amplifier, but biased to conduct less than 50% of time



The output amplitude is not a linear function of input: more suitable for constantamplitude power amp (such as in PM or FM)

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Class C Amplifier Waveforms



$$i_D = I_{DC} + i_{rf} sinw_o t$$
$$i_D > 0, I_{DC} < 0$$

Conduction angle

$$2\phi = 2 \cdot \cos^{-1} \left(-\frac{I_{DC}}{i_{rf}} \right)$$

Solving for the DC bias to achieve conduction angle ϕ

$$I_{DC} = -i_{rf} cos\phi$$

Class C Power Efficiency Calculation

The average value of i_D is

$$\begin{split} \overline{i_D} &= \frac{1}{2\pi} \int_{-\phi}^{\phi} \left(I_{DC} + i_{rf} \cos\phi \right) d\phi \\ = \frac{1}{2\pi} 2\phi I_{DC} + \frac{1}{2\pi} \left[i_{rf} \sin\phi \right]_{-\phi}^{\phi} \\ I_{DC} &= \frac{i_{rf}}{\pi} \left(\sin\phi - \phi \cos\phi \right) \end{split}$$

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The fundamental component of i_D is

$$i_{fund} = \frac{2}{T} \int_0^T i_D \cos w_o t dt = \frac{1}{2\pi} (4I_{DC} \sin \phi + 2i_{rf} \phi + i_{rf} \sin 2\phi)$$
$$= \frac{i_{rf}}{2\pi} (2\phi - \sin 2\phi)$$

Maximum output swing is reached when

$$i_{fund}R_L = V_{DD}$$

Class C Power Efficiency, Continued

Solving for i_{rf}:

$$i_{rf} = \frac{2\pi V_{DD}}{R(2\phi - sin2\phi)}$$

Peak drain current

$$i_{D,max} = I_{DC} + i_{rf}$$

$$= \frac{i_{rf}}{\pi} (sin\phi - \phi cos\phi) + \frac{2\pi V_{DD}}{R(2\phi - sin2\phi)}$$

$$= \frac{2\pi V_{DD}}{R(2\phi - sin2\phi)} \left[1 + \frac{(sin\phi - \phi cos\phi)}{\pi} \right]$$

$$\phi \rightarrow 0: i_{rf} \rightarrow \infty, i_{D,max} \rightarrow \infty$$

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Class C Power Efficiency, Continued

Maximum efficiency is then

$$\eta = \frac{2\phi - \sin 2\phi}{4(\sin \phi - \phi \cos \phi)} \qquad \phi \to 0 : \eta \to 1$$

The normalized output capability is poor at small conduction angles

$$v_{DS,max} = 2V_{DD}$$

 $\phi \to 0 : i_{D,max} \to \infty, P_N \to 0$

Thus, the efficiency must be sacrificed for reasonable P_N

Class D Power Amplifier

- Ideal switches dissipate no power (either v or i is zero)
- Thus, highest efficiency will be achieved by operating active devices as switches.
- Push-pull Class D amplifier example



Load tank circuit is series LC, because the switch has low impedance when on (in contrast to a current-source like behavior in other class amplifiers)

Class D Push-Pull Power Amplifier Waveforms



Class D Secondary Winding Waveforms



Class B vs. D Push-Pull Amplifier Waveforms



Class D Amplifier Power Efficiency

- With ideal switches, Class D amplifier efficiency would be 100%
- In practice, finite switch ON resistance and nonzero on-off transients limit efficiency (use high f_t device!)
- In bipolar Class D amplifier, the efficiency is further compromised due to charge storage in saturation and V_{CE,SAT}.
- Normalized power capability is shown to be

$$P_N = \frac{P_L}{v_{DS,max} \cdot i_{D,max}} = \frac{1}{\pi} = 0.32$$

Class E Power Amplifier

- Finite switching speed causes v-i product at the switching instant non-zero -> power loss
- Class E amplifier tries to make both v and i zero at the off-to-on transient (solves only half of the problem)



Typical Voltage and Current Wavforms



Souce: Shawn Kuo, "Linearization of a PulseWidth Modulated Power Amplier," S.B. Thesis, MIT, June 2004

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Class E Amplifier Design and Efficiency

- For detailed design equations and analyses, refer to Tom Lee's book and
 N.O. Sokal and A.D. Sokal, "Class E, a New Class of High-Efficiency Tuned Single-Ended Power Amplifiers," IEEE J. Solid-State Circuits, v.10, June 1975, pp 168-176
 (Original invention of Class E by G. Ewing in 1964)
- Ideal Class E amplifier has 100% efficiency, but in practice, finite ON resistance of MOS switches as well as off-transients reduce efficiency

Normalized Output Power Capability

$$v_{DS,max} \approx 3.6V_{DD}, i_{D,max} \approx 1.7 \frac{V_{DD}}{R}$$

 $P_{L,max} = \frac{2}{1 + \frac{\pi^2}{4}} \approx 0.577 \cdot \frac{V_{DD}^2}{R} \quad P_N = \frac{P_{L,max}}{v_{DS,max} \cdot i_{D,max}} \approx 0.098$

Due to very low P_N, Class E amplifiers are more suitable for low frequency amplifiers in which large devices can be used

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Class F Power Amplifier

- Allows square wave on drain
- Single-ended version of Class D



Class F Power Amplifier Waveforms

The waveforms are similar to half of Class-D Push-Pull



Class F Power Amplifier Analysis

Refer to Tom Lee's book

Amplitude of fundamental frequency of drain voltage $v_{fund} = \frac{4}{\pi} \cdot V_{DD}$

Power delivered to the load

$$P_{L} = \frac{v_{fund}^{2}}{2R} = \frac{8V_{DD}^{2}}{\pi^{2}R}$$
$$i_{D,max} = \frac{4}{\pi} \cdot \frac{2V_{DD}}{R} = \frac{8V_{DD}}{\pi R} \qquad v_{DS,max} = 2V_{DD}$$
$$P_{N} = \frac{v_{fund}^{2}}{2R} = \frac{8V_{DD}^{2}}{\pi^{2}R} / \left(2V_{DD} \cdot \frac{8V_{DD}}{\pi R}\right) = \frac{1}{2\pi} \approx 0.16$$

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