6.852: Distributed Algorithms Fall, 2009

Class 17

Today's plan

- Atomic objects:
 - Basic definitions
 - Canonical atomic objects
 - Atomic objects vs. shared variables
- Reading: Sections 13.1-13.2
- Next time:
 - More atomic objects:
 - Atomic snapshots
 - Atomic read/write registers
 - Reading: Sections 13.3-13.4

Shared memory model

- Single I/O automaton with processes and variables "inside".
 - Separation expressed by locality restrictions on the actions and transitions.
 - Processes and variables aren't separate automata.
 - Doesn't exploit I/O automaton (de)composition.
 - Can't talk about implementing shared variables with lower-level distributed algorithms.
- Q: Could we model each process and variable as a separate I/O automaton?
 - Split operations on variables into separate invocation and response actions.
 - But we still want an invocation/response to "look like" an instantaneous access.
- Define atomic objects:
 - Interface has invocation inputs and response outputs.
 - Invocation/response behavior "looks like" that of an instantaneous-access shared variable.
 - AKA linearizable objects [Herlihy, Wing]



Atomic objects

- Interface has invocation inputs and response outputs.
- Invocation/response behavior "looks like" that of an instantaneous-access shared variable.
- Atomic object of a given type is similar to an ordinary shared variable of that type, but it allows concurrent accesses by different processes.
- Still looks "as if" operations occur one at a time, sequentially, in some order consistent with order of invocations and responses.
- Fault-tolerance conditions, as for consensus:
 - Wait-free termination
 - f-failure termination
- Separating invocations and responses allows us to consider lower-level implementations of these objects.
 - Shared-memory algorithms, or distributed network algorithms.
 - For shared memory algorithms, can develop algorithms hierarchically, using several levels.
- Atomic objects are important building blocks for multiprocessor systems and distributed systems.



Replacing variables with atomic objects

- Now processes and objects are all I/O automata, combined using ordinary automata composition.
- Interactions:
 - Processes access atomic objects via invocations, get responses.
 - Invocations are outputs of processes, inputs of objects.
 - Responses are outputs of objects, inputs of processes.
 - May be a gap between invocation and response.





Replacing variables with atomic objects

- "Locality" is now automatic from I/O automata composition.
- More complicated than shared variables:
 - More actions (invocations/responses instead of entire accesses).
 - Algorithms have more steps, more bookkeeping.
 - More stuff to reason about.
- More realistic system model.





Atomic objects

- Replace variables with atomic objects
 - -can decompose system in different ways
 - what a process is depends on your point of view
 - can compose objects into larger objects





- -but we need some restrictions to get "equivalance"
- -handling failures, in particular, is tricky
 - delay for later in lecture





Atomic objects: Basic definitions

Atomic object definitions

- Variable type: (V, v₀, invs, resps, f)
 - V: Set of values
 - v₀: Initial value
 - invs: Set of invocations
 - resps: Set of responses
 - f: invs \times V \rightarrow resps \times V
 - Describes responses to an invocation and associated changes to the variable.
- AKA Sequential specification [Herlihy], State machine [Lamport]
- Execution: $v_0, a_1, b_1, v_1, a_2, b_2, v_2, a_3, b_3, v_3, a_4, b_4, v_4, \dots$
 - $-v_i$ is value; a_i is invocation; b_i is response
 - Ends with value (if finite).
 - $(b_i, v_i) = f(a_i, v_{i-1})$ for i > 0.
- Trace: a₁, b₁, a₂, b₂, a₃, b₃, a₄, b₄,... (i.e., just invocations and responses, but no variable values)

Atomic objects

- Atomic object A of a given type is an I/O automaton with a particular kind of interface, satisfying some conditions:
 - Well-formedness
 - Atomicity
 - Liveness (termination)
- External interface:
 - Assume "ports" 1, 2, ..., n (one for each process).
 - May restrict so that some invocations are allowed on some of the ports, not all.
 - Also allow stop inputs on all ports, as before.
- Compose with users U_i, assumed to preserve well-formedness (alternating invocations and responses at each port, starting with invocation).



Conditions satisfied by A

- Preserves well-formedness (alternating invocations and responses at each port, starting with invocation).
- Atomicity:
 - First define when a well-formed sequence β of invocations and responses (at all ports) is atomic.
 - Then A satisfies atomicity iff all well-formed executions of $A \times U$, where $U = \Pi U_i$ (for any users) have atomic traces.
- First suppose that all invocations have matching responses (that is, the sequence β is complete).
- Then we say β is atomic provided that it's possible to insert a serialization point (dummy event) somewhere between each invocation and matching response, such that, if all the invs and resps are moved to their serialization points, the result is a trace of the (serial) variable type.

Atomicity for complete sequences

 Suppose β is a complete well-formed sequence of invocations and responses.

Then β is atomic provided that one can insert a serialization point between each invocation and matching response, such that, if all the invs and resps are moved to their serialization points, the result is a trace of the (serial) variable type.

• Examples: Initial value 0.



- read, 0, write(8), ack is correct for serial specification.
- write(8), ack, read, 8 is also correct.

Alternative definition [Herlihy]

- Suppose β is a complete well-formed sequence of invocations and responses. Then β is atomic provided that it can be reordered to a trace of the variable type, while preserving:
 - The order of events at each process, and
 - The order of any response and following invocation (anywhere).
- Equivalent.

Complication: Incomplete operations

- Q: What about sequences β containing some incomplete operations? Which ops should get serialization points?
- We can't require that we include serialization points for all such operations (operation might fail right after invocation).
- We can't require that we exclude all such operations (operation might fail just before returning).
- So, we leave it optional...
- Require that it's possible to:
 - Insert serialization points for all complete operations.
 - Select some subset Φ of incomplete operations (arbitrary).
 - For each operation in Φ , insert a serialization point somewhere after the invocation, and make up a response.
 - In such a way that moving all matched invs and their resps to the serialization points yields a trace of the variable type.

Atomic sequences, in general

 Suppose β is any well-formed sequence of invocations and responses.

Then β is atomic provided that one can

- Insert serialization points for all complete operations.
- Select a subset Φ of incomplete operations.
- For each operation in Φ , insert a serialization point somewhere after the invocation, and make up a response.
- In such a way that moving all matched invs and their resps to the serialization points yields a trace of the variable type.

More atomicity examples

• Initial value 0.



- read, 0 is correct for serial specification.
- write(8), ack, read, 8 is correct.

Atomic objects

- Define acceptable behavior using trace properties
 - -well-formedness (for port i)
 - alternating invocation/response (beginning with invocation) for i
 - whole trace is well-formed if well-formed for every port
 - -sequential
 - alternating invocation/response for whole trace
 - trace for the variable type
 - complete
 - every invocation has matching response
 - invocation+matching response = complete operation
 - invocation without matching response = incomplete/pending operation

Another atomicity example

Initial value 0.



- read, 0, read, 0,...(forever) is correct.
- The write does not (cannot) get a serialization point.

Some non-atomic sequences

• Write not seen:



• Out-of-order reads



Note on the atomicity property

- [Well-formedness + atomicity] is a safety property.
- More precisely, let P be the trace property, for sequences of invocations and responses, expressing:
 - Well-formedness for every port, plus
 - Atomicity.

Then P is a safety property.

- In other words, if this combination doesn't hold, the violation occurs at some particular point in the sequence.
- Plausible, but not completely obvious---proved in book, p. 405.
 - Uses Konig's Lemma to show limit-closure.
 - That is, if we can assign serialization points correctly to successively-extended finite sequences, then there is a way to assign them to their infinite limiting sequence.

Back to the conditions satisfied by an atomic object A...

- Preserves well-formedness.
- Atomicity:
 - We just defined when a well-formed sequence β of invocations and responses (at all ports) is atomic.
 - Then A satisfies atomicity iff all well-formed executions of $A \times U$, where $U = \Pi U_i$ (for any users) have atomic traces.
- Liveness (termination):

Liveness

- Failure-free termination (basic requirement for atomic objects):
 - In any fair failure-free execution of $A \times U$, every invocation has a matching response.
 - "Fair" here refers to fairness in the underlying
 I/O automata model---A keeps taking steps.
- Definition: A is an atomic object if it satisfies well-formedness, atomicity, and failure-free termination (for all U).

Other liveness conditions

- As for consensus, we sometimes consider other liveness conditions, expressing fault-tolerance properties.
- Wait-free termination: In any fair execution of A × U, every invocation on a non-failing port gets a response.
- f-failure termination, 0 ≤ f ≤ n: In any fair execution of A × U in which failures occur on ≤ f ports, every invocation on a non-failing port gets a response.

Example: A wait-free atomic object

- Variable type:
 - Natural numbers, initial value 0.
 - read and increment operations.
- Atomic object supports read and increment ops on all ports.
- Implement with an n-process shared-memory system.
- Shared read/write registers
 - x(i), $1 \le i \le n$, natural number, initially 0.
 - x(i) writable by i, readable by all.
- To implement increment_i: Process i increments its own variable x(i).
 - Can do this using a write operation, by remembering the previous value written.
- To implement read_i: Process i reads all the shared variables, one at a time, in any order, and returns the sum.
- Q: Why does this work?

Read/Increment algorithm

- increment_i: Increment x(i).
- read_i: Read all the shared variables, one at a time, in any order, and return the sum.
- Proof:
 - Well-formed, wait-free: Immediate.
 - Atomic: Say where to put the serialization points.
 - For increment: At the actual write step.
 - For complete read:
 - Must be somewhere between invocation and response.
 - Returns a value v such that $v \ge$ the sum of the x's at the beginning, but v \le the sum at the end.
 - Since the sum increases by one at a time, there is some point where sum of the x's = v.
 - Put the serialization point there.
 - For incomplete read: Don't bother.
- Correctness depends on restricted form of the operations.

Canonical Atomic Object Automata

- Describe the set of traces acceptable for a wait-free atomic object as the fair traces of a particular canonical object automaton; see Section 13.1.2.
- Could generalize to f-failure termination (see later).
- Canonical object automaton keeps internal copy of the variable, plus delay buffers for invocations and responses.
- Behavior: 3 kinds of steps:
 - Invoke: Invocation arrives, gets put into in-buffer.
 - Perform: Invoked operation gets performed on the internal copy of the variable, response gets put into resp-buffer.
 - Respond: Response returned to user.
- Internal perform step is convenient, even though we're interested only in specifying external behavior.
- Perform step corresponds to serialization point.

• Liveness:

- One task for each port i.
- Use the usual I/O automata convention that tasks keep getting turns to take steps.
- To model the effects of failures, we include a specially dummy_i action in each task i, which gets enabled when stop_i occurs.

- Equivalent to the original specification for a waitfree atomic object, in a precise sense.
- Can be used to prove correctness of algorithms that implement atomic objects, e.g., using simulation relations.
- Theorem 1: Every fair trace of the canonical automaton (with well-formed U) satisfies the properties that define a wait-free atomic object.
- Theorem 2: Every trace allowed by a wait-free atomic object (with well-formed U) is a fair trace of the canonical automaton.

- An equivalent definition as an automaton C
 - -external actions as before
 - internal actions: perform(a,i)
 - -state variables:
 - val: V, initially v_0
 - inv_buffer: set of (i,a), initially empty
 - resp_buffer: set of (i,b), initially empty
 - -transitions:
 - inv(a,i) adds (i,a) to inv_buffer
 - perform(a,i) removes (i,a) from inv_buffer, applies a to val, and puts (i,b) into resp_buffer, where b is the response from applying a to val
 - resp(b,i) takes (i,b) removes resp_buffer
 - -one task for each i

- For C and U as defined previously:
 - $-\mathbb{R} \square traces(C \times U)$ iff \mathbb{R} is well-formed and atomic
 - -® □ fairtraces(C×U) iff ® is well-formed, atomic and complete
- Proof
 - -well-formedness
 - -atomicity
 - -completeness
 - -need to show both directions
- An automaton A is atomic if it implements C.

Atomic Objects vs. Shared Variables

Atomic objects vs. shared vars

- Atomic objects aren't the same as shared variables.
- But an important basic result says we can substitute atomic objects for shared variables in a shared-memory system, and the resulting system "behaves the same".
- Enables hierarchical construction of sharedmemory systems.



• The substitution:

- Given A, a shared-memory system, and
- For each shared variable x of A, given an atomic object B_x (same type, interface corresponding to the allowed connections).
- Trans is the composition of I/O automata, one for each process and variable.

Atomic objects vs. shared vars

- Given shared-memory system A, and for each shared variable x of A, given atomic object B_x.
- Trans is the composition of I/O automata, one for each process and variable:
 - For variable x, use atomic object B_x .
 - For process i, use automaton P_i, where:
 - Inputs of P_i are inputs of A on port i, responses of all the B_xs on port i, and stop_i.
 - Outputs of P_i are outputs of A on port i and invocations to all the B_xs on port i.
 - Steps of P_i simulate those of process i of A directly, except when process i of A accesses x, Then P_i invokes the operation on B_x, then blocks, waiting for a response. When response arrives, P_i resumes simulating process i.



Atomic objects vs. shared vars

- A note on failure actions:
 - $stop_i$ is an input both to P_i , and to all objects B_x that P_i is connected to.



What is preserved by this transformation?

- Theorem: For any execution α of Trans × U, there is an execution α' of A × U (that is, of the original shared-memory system) such that:
 - $-\alpha \mid U = \alpha' \mid U$ (looks the same to the users), and
 - stop_I events occur for the same i in α and α' (the same processes fail).
- Technicality: Need a little assumption about A---that at any point, for each i, either process i or the user at i is enabled to do something, but not both.
- **Proof:** Given α , construct α' :
 - Introduce serialization points and responses for operations of ${\sf B}_{\sf x}$ in $\alpha,$ as guaranteed by the atomicity definition.
 - Then commute the invocation and responses events with other events until they appear next to their serialization points.

What is preserved?

- Theorem: For any execution α of Trans × U, there is an execution α' of A × U such that:
 - $\alpha \mid U = \alpha' \mid U \text{ and }$
 - stop_I events occur for the same i in α and α' .
- **Proof:** Given α , construct α' :
 - Introduce ser. pts. and responses for operations of B_x in α .
 - Commute invocation and responses events with other events until they appear next to their serialization points.
 - OK as far as the B_x s are concerned.
 - What about the P_i s? We aren't allowed to reorder events of the same P_i .
 - But no such reordering happens, because:
 - P_i blocks when it performs invocations, and
 - No inputs arrive at P_i from U while P_i is waiting for a response to an invocation (by the technical assumption---it's the system's turn).
 - Result is still an execution of Trans × U (using composition results), but now it's one with all invocations and responses occurring in consecutive pairs.
 - Now replace the pairs with single access steps.

Liveness

- Construction also preserves liveness:
- Can show that α fair implies α' fair, that is, that a fair execution of Trans \times U emulates a fair execution of A \times U.
- The difficulty: Objects sometimes don't respond to invocations, whereas shared variable accesses always return. So the objects could introduce new blocking.
- We need an assumption that implies that the objects don't introduce new blocking.
- E.g., can assume that the B_x objects are wait-free.
- E.g., can assume that at most f failures occur in α and each B_x guarantees f-failure termination.
 - "The failures that happen are tolerated by the objects."
 - Ensures that the objects always respond to non-failed processes.

Application 1 of Trans results

- Implementing atomic objects using other atomic objects:
 - Suppose A is itself an atomic object implementation, using shared memory.
 - Say A and all the B_xs guarantee f-failure termination.
 - Then Trans also implements an atomic object (of the same type), and guarantees f-failure termination.

Application 2 of Trans results

- Building shared-memory systems hierarchically.
 - Suppose the B_xs are themselves shared-memory systems implementing atomic objects.
 - Then Trans yields a 2-level system:
 - If we compose each P_i at the top level with all the i-port agent processes within the B_x implementations, we get an actual shared-memory system (processes and variables).



Combining the two applications

- Building shared-memory implementations of atomic objects hierarchically.
 - Same as Application 2, but top level system is itself an atomic object implementation, as in Application 1.
 - Shows how to combine shared-memory implementations of atomic objects at two levels to get a single shared-memory implementation of the top-level atomic object.
 - Used implicitly in the research literature.



Algorithms to implement atomic objects

Read-Modify-Write Atomic Object

- Can we implement a general RMW atomic object using just read/write shared variables?
- Non-fault-tolerant implementation:
 - Use lockout-free mutex algorithm, e.g., one of Peterson's.
 - Simulate the RMW variable using a read/write register.
 - Access the register only within critical region, using a read followed by a write.
- Q: Fault-tolerant implementation?



Read-Modify-Write Atomic Object

- Fault-tolerant implementation?
- Say,1-failure termination.
- Theorem: There is no shared memory system using only read/write shared variables that implements a general RMW atomic object and guarantees 1-failure termination.
- **Proof:** By contradiction.
 - Suppose there is, system B.
 - Let A be a RMW-based agreement algorithm that uses 1 shared RMW variable and guarantees 1-failure termination.
 - Earlier, we saw how to guarantee wait-free termination.
 - Substitute B for the RMW shared variables in A.
 - Resulting system solves agreement in read/write model, with 1failure termination.
 - Contradicts impossibility result for consensus.

Next time:

- More algorithms to implement atomic objects:
 - Atomic snapshots
 - Atomic read/write registers
- Reading: Sections 13.3-13.4

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