6.895 Essential Coding Theory

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Lecture 6

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Remark: We defer the proof of the next statement to some later lecture.(it occurred in the proof of Plotkin bound in the last lecture):

if  $x_1, \ldots, x_m \in \mathbb{R}^n$  satisfy  $\forall i \neq j, < x_i, x_j > \leq 0$  then,  $m \leq 2n$ .

## 1 Overview

In this lecture we will examine some topics of decoding codes. Especially we will study Welch-Berlekamp algorithm, an error detecting decoding algorithm for Reed Solomon Codes(RS Codes).

# 2 Decoding linear codes

When we encode or decode linear codes, the some problems of finding efficient algorithm arise.

- Encoding codes: by multiplying the generator matrix, complexity of encoding any linear code is  $O(n^2)$ .<sup>1</sup>
- Detecting errors : For any linear codes, if the number of errors is less than d, we can detect errors in  $O(n^2)$  since it only involves multiplication by H, the error check matrix.
- Decoding from erasures
- Decoding from erroneous codes: This is one of the main topics in codes decoding and in this lecture we will cover one algorithm for RS codes decoding.

## 3 Decoding from erasure

Given a generator matrix G, and a codeword  $y \in (\sum \cup \{?\})^n$  where '?' represents an erasure, Goal: find x such that xG is consistent with y.

Note that if  $y_i \neq ?$ ,  $(xG)_i = x(G_i) = y_i$  because xG is consistent with y. (Here,  $G_i$  refers to the *i*th column of G)

Now construct G' consisting of such *i*th columns of G, and y' consisting of non ? elements of y. If the number of erasure is less than d, than because  $d \leq n - k + 1$ , we can obtain unique x such that xG' = y'. Then this is the required x.

## 4 Welch-Berlekamp algorithm for RS codes decoding('86)

### 4.1 Brief history for RS codes decoding

- 1958,1959 BCH codes were discovered.
- 1960 Peterson gave a polynomial time algorithm for decoding BCH codes.
- 1963 Gorenstein Zierler saw that BCH codes and RS codes have a common generalization. And the decoding algorithm extends to more general situation.
- 1968 Berlekamp, Massey gave more efficient algorithm to decode BCH, RS codes.

<sup>&</sup>lt;sup>1</sup>Some codes have lower encoding complexity. For example there exists an  $O(n(logn)^{O(1)})$  algorithm for encoding RS codes. There even exist some linear-time encoding codes

#### 4.2 Error-locator polynomial

Let's recall the RS decoding problem. In this problem inputs are pairwise distinct  $\alpha_i$ 's (i = 1...n) and a codeword  $y = (y_1, \ldots, y_n) \in \mathbb{F}^n$ . Now our goal is to find a polynomial P over  $\mathbb{F}$  such that P has degree less than k and (the number of *i*'s s.t.  $P(\alpha_i) \neq y_i$ )  $\leq \frac{d-1}{2} = \frac{n-k}{2}$ . Note that the coefficients of P are the encoded information.

To solve this problem, we may think of an indicator for the *i*'s where error occurred. To this end, we will define a Error-locator polynomial E(x). E(x) will be a polynomial over  $\mathbb{F}$  such that  $E(\alpha_i) = 0$  if  $y_i \neq P(\alpha_i)$  and the degree of *E* is less than or equal to  $\frac{n-k}{2}$ .

Claim 1 Error locator polynomial exists.

Proof

Let  $S = \{\alpha_i | P(\alpha_i) \neq y_i\}$ Then let  $E(x) = \prod_{\alpha_i \in S} (x - \alpha_i).$ 

Now, define N(x) a polynomial over  $\mathbb{F}$  by N(x) = E(x)P(x). Then E(x) and N(x) have following properties.

- $deg(E) \leq \frac{n-k}{2}$
- $E \neq 0$
- $deg(N) \le \frac{n-k}{2} + (k-1) = \frac{n+k}{2} 1$

• 
$$\forall i \ N(\alpha_i) = E(\alpha_i)y_i$$

•  $\frac{N}{E} = P$ 

The proofs for the above properties are straightforward. Now we introduce Welch-Berlekamp Algorithm. it uses above properties of E and N.

### 4.3 Welch-Berlekamp Algorithm

#### Welch-Berlekamp Algorithm

Find two polynomials  $E_0(x)$ ,  $N_0(x)$  such that

- 1.  $degE_0 = fracn k2$ , the highest coefficient of  $E_0$  is 1.
- 2.  $deg N_0 \le \frac{n-k}{2} + (k-1) = \frac{n+k}{2} 1$
- 3.  $\forall i \ N_0(\alpha_i) = E_0(\alpha_i)y_i$

We can find these  $E_0$  and  $N_0$  using *n* linear equations of 3) over  $\frac{n-k}{2} + \frac{n+k}{2} = n$  unknown coefficients of  $E_0$  and  $N_0$ . It can be performed in  $O(n^3)$  time.

Let the output of this algorithm be  $\frac{N_0}{E_0}$ .

**Lemma 2** If  $(N_1, E_1)$  and  $(N_2, E_2)$  are two solutions satisfying above 1), 2), 3), then

$$\frac{N_1}{E_1} = \frac{N_2}{E_2}$$
(1)

#### Proof

For all i,  $N_j(\alpha_i) = E_j(\alpha_i)y_i$ . If  $y_i \neq 0$ , we obtain

$$N_1(\alpha_i)E_2(\alpha_i) = N_2(\alpha_i)E_1(\alpha_i) \tag{2}$$

by multiplying  $N_1(\alpha_i) = E_1(\alpha_i)y_i$  and  $E_2(\alpha_i)y_i = N_2(\alpha_i)$  side by side. If  $y_i = 0$ ,  $N_1(\alpha_i) = N_2(\alpha_i) = 0$ . So (2) still holds. Therefore (2) holds for all *i*. Then because  $N_1E_2$  and  $N_2E_1$  have degrees less than *n*, they must be identical.

Now, it can be easily checked that for some polynomial R(x) with degree  $\frac{n-k}{2} - deg(E)$ , (E(x)R(x), N(x)R(x)) is one solution for 1), 2), 3). And by definition of N(x), it also can be easily checked that  $\frac{N \cdot R}{E \cdot R} = P$ . So for any solution  $(N_0, E_0)$  of 1), 2), 3),  $\frac{N_0}{E_0} = P$  as expected.

## 5 Abstracting the algorithm

In this section, we will try to generalize the condition given for the Welch-Berlekamp algorithm. When we consider E, N, P of Welch-Berlekamp algorithm, E is an element of set A of all the polynomials with degree  $\frac{n-k}{2}$  or less. Similarly N is an element of set B of all the polynomials with degree  $\frac{n+k}{2} - 1$  or less, and P is an element of set C of all the polynomials with degree k - 1 or less.

Then the problem we need to solve is,

Given (A, B, C) and  $y = (y_1, y_2, \ldots, y_n)$  such that y is (in some sense) close to some element of C, Find  $E \in A$ ,  $N \in B$  such that  $E \neq 0$  and  $\forall i \ E_i y_i = N_i$ .

More precise description and analysis of this generalization will be given in the next lecture.