Bayes Procedures

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1 Bayes Procedures

• Decision-Theoretic Framework

Bayes Procedures

Decision Problem: Basic Components

- $\mathcal{P} = \{ P_{\theta} : \theta \in \Theta \}$: parametric model.
- $\Theta = \{\theta\}$: Parameter space.
- $\mathcal{A}{a}$: Action space.
- $L(\theta, a)$: Loss function.
- $R(\theta, \delta) = E_{X|\theta}[L(\theta, \delta(X))]$

Decision Problem: Bayes Components

- π : Prior distribution on Θ
- $r(\pi, \delta) = E_{\theta}[R(\theta, \delta)] = E_{\theta}[E_{X|\theta}[L(\theta, \delta(X)]] = E_{X,\theta}[L(\theta, \delta(X))]$ "Bayes risk of the procedure $\delta(X)$ with respect to the prior π ."
- $r(\pi) = \inf_{\delta \in \mathcal{D}} r(\pi, \delta)$: Minimum Bayes risk.
- δ_{π} : $r(\pi, \delta_{\pi}) = r(\pi)$

" Bayes rule with respect to prior π and loss $L(\cdot, \cdot)$."

Bayes Procedures: Interpretations of Bayes Risk

Bayes risk

$$r(\pi,\delta) = \int_{\Theta} R(\theta,\delta)\pi(d\theta)$$

- $\pi(\cdot)$ weights $\theta \in \Theta$ where $R(\theta, \delta)$ matters.
- π(θ) = constant: weights θ uniformly.
 Note: uniform weighting depends on parametrization.
- Interdependence of specifying the loss function and prior density:

$$\begin{aligned} r(\pi,\delta) &= \int_{\Theta} \int_{\mathcal{X}} [L(\theta,\delta(x))\pi(\theta)] p(x \mid \theta) dx \ d\theta. \\ &= \int_{\Theta} \int_{\mathcal{X}} [L^*(\theta,\delta(x))\pi^*(\theta)] p(x \mid \theta) dx \ d\theta. \end{aligned}$$

for $L * (\cdot, \cdot), \ \pi^*(\cdot)$ such that
 $L^*(\theta,\delta(x))\pi^*(\theta) = L(\theta,\delta(x))\pi(\theta)$

Bayes Procedures: Quadratic Loss

Quadratic Loss: Estimating $q(\theta)$ with $a \in \mathcal{A} = \{q(\theta), \theta \in \Theta\}$. $L(\theta, a) = [q(\theta) - a]^2$.

• Bayes risk: $r(\pi, \delta) = E([q(\theta) - \delta(X)]^2)$

- Bayes risk as expected Posterior Risk: $r(\pi, \delta) = E_X(E_{\theta|X}L(\theta, \delta(X)))$ $= E_X(E_{\theta|X}([q(\theta) - \delta(x)]^2))$
- Bayes decision rule specified by minimizing: $E_{\theta|X}([q(\theta) - \delta(x)]^2 \mid X = x)$ for each outcome X = x, which is solved by $\delta_{\pi}(x) = E_{\theta|X=x}[q(\theta) \mid X = x]$ $= \frac{\int_{\Theta} q(\theta)p(x \mid \theta)\pi(\theta)d\theta}{\int_{\Theta} p(x \mid \theta)\pi(\theta)d\theta}$

Bayes Procedure: Quadratic Loss

Example 3.2.1 X_1, \ldots, X_n iid $N(\theta, \sigma^2), \sigma^2 > 0$, known. **Prior Distribution:**

$$\pi: \theta \sim N(\eta, \tau^2).$$

Posterior Distribution:

$$\theta \mid X = x :\sim \mathcal{N}(\eta_*, \tau_*^2)$$

where $\eta_* = [\frac{1}{\sigma^2/n}\overline{X} + \frac{1}{\tau^2}\eta]/[\frac{1}{\sigma^2/n} + \frac{1}{\tau^2}]$
 $\tau_*^2 = [\frac{1}{\sigma^2/n} + \frac{1}{\tau^2}]^{-1}.$

Bayes Procedure: $\delta_{\pi}(X) = E[\theta \mid x] = \eta_*$ Observations:

• Posterior risk:
$$E[L(\theta, \delta_{\pi}) | X = x] = \tau_*^2$$
 (constant!)
 \implies Bayes risk: $r(\pi, \delta_{\pi}) = \tau_*^2$.

• MLE
$$\delta_{MLE}(\mathbf{x}) = \overline{\mathbf{x}}$$
 has
Constant Risk: $R(\theta, \overline{\mathbf{X}}) = \sigma^2/n$
 \implies BayesRisk: $r(\theta, \overline{\mathbf{X}}) = \sigma^2/n$ (> τ_*^2)
• $\lim_{\tau \to \infty} \delta_{\pi}(\mathbf{x}) = \overline{\mathbf{x}}$ and $\lim_{\tau \to \infty} \tau_*^2 = \sigma_{\Box}^2/n$.

Bayes Procedure: General Case

Bayes Risk and Posterior Risk:

$$r(\pi, \delta) = E_{\theta}[R(\theta, \delta(X)] = E_{\theta}[E_{X|\theta}[L(\theta, \delta(X))]]$$

$$= E_{X}[E_{\theta|X}[L(\theta, \delta(X))]]$$

$$= E_{X}[r(\delta(X) | X)]$$

where

$$r(a \mid x) = E[L(\theta, a) \mid X = x]$$
 (Posterior risk)

Proposition 3.2.1 Suppose $\delta^* : \mathcal{X} \to \mathcal{A}$ is such that $r(\delta^*(x) \mid a) = \inf_{a \in \mathcal{A}} \{r(a \mid x)\}$ Then δ^* is a Bayes rule. Proof. For any procedure $\delta \in \mathcal{D}$, $r(\pi, \delta) = E_X[r(\delta(x) \mid x)]$ $\geq E_X[r(\delta^*(x) \mid x)]$ $= r(\pi, \delta^*)$.

Bayes Procedures for Problems With Finite Θ

$\textbf{Finite}~\Theta~\textbf{Problem}$

•
$$\Theta = \{\theta_0, \theta_1, ..., \theta_K\}$$

• $\mathcal{A} = \{a_0, a_1, ..., a_q\}$ (*q* may equal *K* or not)
• $L(\theta_i, a_i) = w_{ii}$, for $i = 0, 1, ..., K$, $j = 0, 1, ..., q$

- Prior distribution: $\pi(\theta_i) = \pi_i \ge 0, i = 1, \dots, K$ $(\sum_{i=1}^{K} \pi_i = 1).$
- Data/Random variable: $X \sim P_{\theta}$ with density/pmf $p(x \mid \theta)$.

Solution:

Posterior probabilities:

$$\pi(\theta_i \mid X = x) = \frac{\pi_i p(x \mid \theta_i)}{\sum_{j=0}^{K} \pi_j p(x \mid \theta_j)}$$

Posterior risks:

$$r(a_j \mid X = x) = \frac{\sum_{i=0}^{K} w_{ij}\pi_i p(x \mid \theta_i)}{\sum_{i=0}^{K} \pi_i p(x \mid \theta_i)}$$

• Bayes decision rule: $\delta^*(x)$ satisfies $r(\delta^*(x) \mid x) = \min_{0 \le j \le K} r(a_j \mid x)$

Finite Θ Problem: Classification

Classification Decision Problem

- p = q, identify ${\cal A}$ with Θ
- Loss function:

$$L(\theta_i, a_j) = w_{ij} = \begin{cases} 1 & if \quad i \neq j \\ 0 & if \quad i = j \end{cases}$$

• Bayes procedure minimizes Posterior Risk $\begin{aligned} r(\theta_i \mid x) &= P[\theta \neq \theta_i \mid x] \\ &= 1 - P[\theta = \theta_i \mid x] \\ &\implies \delta^*(x) = \theta_i \in \mathcal{A}, \text{ that maximizes } P[\theta = \theta_i \mid x]. \end{aligned}$

Special case: Testing Null Hypothesis vs Alternative

• p = q = 1

•
$$\pi_0 = \pi, \ \pi_1 = 1 - \pi_0$$

- Testing $\Theta_0 = \{\theta_0\}$ versus $\Theta_1 = \{\theta_1\}$
- Bayes rule chooses $\theta = \theta_1$ if $P[\theta = \theta_1 \mid x] > P[\theta = \theta_0 \mid x]$.

Finite Θ Problem: Testing

Equivalent Specifications of Bayes Procedure: $\delta^*(x)$

• Minimizes

$$r(\pi, \delta) = \pi R(\theta_0, \delta) + (1 - \pi)R(\theta_1, \delta)$$

$$= \pi P(\delta(X) = \theta_1 | \theta_0) + (1 - \pi)P(\delta(X) = \theta_0 | \theta_1)$$
• Chooses $\theta = \theta_1$ if
• $P[\theta = \theta_1 | X] > P[\theta = \theta_0 | X]$
• $(1 - \pi)p(x | \theta_1) > \pi p(x | \theta_0)$
• $\frac{p(x | \theta_1)}{p(x | \theta_0} > \pi/(1 - \pi)$ (Likelihood Ratio)
• $\frac{(1 - \pi)}{\pi} \times \frac{p(x | \theta_1)}{p(x | \theta_0)} > 1$ (Bayes Factor)
• The procedure $\delta *$ solves:
Minimize : $P(\delta(X) = \theta_0 | \theta_1)$ $P(Type \ II \ Error)$
Subject to : $P(\delta(X) = \theta_1 | \theta_0) \le \alpha$ $P(Type \ I \ Error)$
i.e., minimizes the Lagrangian:
 $P(\delta(X) = \theta_1 | \theta_0) + \lambda P(\delta(X) = \theta_0 | \theta_1)$
with Lagrange multiplier $\lambda = (1 - \pi)/\pi$.

Estimating Success Probability With Non-Quadratic Loss

Decision Problem: X_1, \ldots, X_n iid Bernoulli(θ)

- $\Theta = \{\theta\} = \{\theta : 0 < \theta < 1\} = (0, 1)$
- $\mathcal{A} = \{a\} = \Theta$
- Loss equal to relative-squared-error: $L(\theta, a) = \frac{(\theta - a)^2}{\theta(1 - \theta)}, \ 0 < \theta < 1 \text{ and } a \text{ real.}$

Solving the Decision Problem

• By sufficiency, consider decision rules based on the sufficient statistic

$$S = \sum_{i=1}^{n} X_i \sim Binomial(n, \theta).$$

• For a prior distribution π on Θ , with density $\pi(\theta)$, denote the density of the posterior distribution by $\pi(\theta \mid s) = [\pi(\theta)\theta^s(1-\theta)^{(n-s)}] / \int_{\Theta} [\pi(t)t^s(1-t)^{(n-s)}] dt$

Solving the Decision Problem (continued)

• The posterior risk $r(a \mid S = k)$ is $r(a \mid S = k) = E[L(\theta, a) \mid S = k)$ $= E[\frac{(\theta - a)^2}{\theta(1 - \theta)} \mid S = k]$ $= E[\frac{\theta}{(1 - \theta)} - \frac{2}{1 - \theta}a + \frac{a^2}{\theta(1 - \theta)} \mid S = k]$ $= E[\frac{\theta}{(1 - \theta)} \mid k] - aE[\frac{2}{1 - \theta} \mid k] + a^2E[\frac{1}{\theta(1 - \theta)} \mid k]$

which is a parabola in a minimized at

$$a = \frac{E[\frac{1}{1-\theta} \mid k]}{E[\frac{1}{\theta(1-\theta)} \mid k]}$$

This defines the Bayes rule $\delta^*(S)$ for S = k (if the expectations exist).

• The Bayes rule can be expressed in closed form when the prior distribution is

$$\theta \sim Beta(r, s) \text{ has closed form solution} \\ \delta^*(k) = \frac{\beta(r+k, n-k+s-1)}{\beta(r+k-1, n-k+s-1)} = \frac{(r+k-1)}{n+r+s-2} \\ \bullet \text{ For } r = s = 1, \ \delta^*(k) = k/n = \overline{X} \text{ (for } k = 0, \ a = 0 \text{ directly}) \\ \bullet = 0 \text{ directly} \quad \text{ for } k = 0 \text{ dir$$

Bayes Procedures Decision-Theoretic Framework

Bayes Procedures With Hierarchical Prior

Example 3.2.4 Random Effects Model

•
$$X_{ij} = \mu + \Delta_i + \epsilon_{ij}, i = 1, ..., I$$
 and $j = 1, ..., J$
 ϵ_{ij} are iid $N(0, \sigma_e^2)$.

- Δ_i iid $N(0, \sigma_{\Delta}^2)$ independent of the ϵ_{ij}
- $\mu \sim N(\mu_0, \sigma_\mu^2)$.

Bayes Model: Specification I

- Prior distribution on $\theta = (\mu, \sigma_e^2, \sigma_{\Delta}^2)$ $\mu \sim N(\mu_0, \sigma_{\mu}^2)$, independent of σ_e^2 and σ_{Δ}^2 . $\pi(\theta) = \pi_1(\mu)\pi_2(\sigma_e^2)\pi_3(\sigma_{\Delta}^2)$.
- Data distribution: $X_{ij} \mid \theta$ are jointly normal random variables with

$$E[X_{ij} \mid \theta] = \mu$$

$$Var[X_{ij} \mid \theta] = \sigma_{\Delta}^{2} + \sigma_{e}^{2}$$

$$Cov[X_{ij}, X_{kl} \mid \theta] = \begin{cases} \sigma_{\Delta}^{2} + \sigma_{e}^{2} & \text{if } i = k, j = l \\ \sigma_{\Delta}^{2} & \text{if } i = k, j \neq l \\ 0 & \text{if } i \neq k \text{ if } i \neq k \text{ solution} \end{cases}$$

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Bayes Procedures With Hierarchical Prior

Example 3.2.4 Random Effects Model

•
$$X_{ij} = \mu + \Delta_i + \epsilon_{ij}$$
, $i = 1, \dots, I$ and $j = 1, \dots, J$
 ϵ_{ij} are iid $N(0, \sigma_e^2)$.

- Δ_i iid $N(0, \sigma_{\Delta}^2)$ independent of the ϵ_{ij}
- $\mu \sim N(\mu_0, \sigma_\mu^2)$.

Bayes Model: Specification II

• Prior distribution on
$$(\mu, \sigma_e^2, \sigma_\Delta^2, \Delta_1, \dots, \Delta_I)$$

 $\pi(\theta) = \pi_1(\mu) \cdot \pi_2(\sigma_e^2) \cdot \pi_3(\sigma_\Delta^2) \cdot \prod_{i=1}^I \pi_4(\Delta_i \mid \sigma_\Delta^2)$
 $= \pi_1(\mu) \cdot \pi_2(\sigma_e^2) \cdot \pi_3(\sigma_\Delta^2) \cdot \prod_{i=1}^I \phi_{\sigma_\Delta}(\Delta_i)$

• Data distribution: $X_{ij} \mid \theta$ are *independent* normal random variables with

$$\begin{split} & E[X_{ij} \mid \theta] = \mu + \Delta_i, \ i = 1, \dots, I, \text{ and } j = 1, \dots, J \\ & Var[X_{ij} \mid \theta] = \sigma_e^2 \end{split}$$

Bayes Procedures with Hierarchical Prior

Issues:

- Decision problems often focus on single Δ_i
- Posterior analyses then require marginal posterior distributions; e.g.

$$\pi(\Delta_1 = d_1 \mid \mathbf{x}) = \int_{\{\theta: \Delta_1 = d_1\}} \pi(\theta \mid \mathbf{x}) \prod_{\{i \text{ except } \Delta_1\}} d heta_i$$

- Approaches to computing marginal posterior distributions
 - Direct computation (conjugate priors)
 - Markov-Chain Monte Carlo (MCMC): simulations of posterior distributions.

Equivariance

Definition

- $\hat{\theta}_M$: estimator of θ applying methodolgy M.
- $h(\theta)$: one-to-one function of θ (a reparametrization).
- $\hat{\theta}_M$ is equivariant if $\widehat{h(\theta)}_M = h(\hat{\theta}_M)$

Equivariance of MLEs and Bayes Procedures

- MLEs are equivariant.
- Bayes procedures not necessarily equivariant
 - For squared error loss, the Bayes procedure is mean of posterior distribution.
 - With non-linear reparametrization $h(\cdot)$,

 $E[h(\theta) \mid x] \neq h(E[\theta \mid x]).$

Bayes Procedures and Reparametrization

Reparametrization of Bayes Decision Problems

- Reparametrization in Bayes decision analysis is not just a transformation-of-variables exercise with the joint/posterior distributions.
- The loss function should be transformed as well.
 If φ = h(θ) and Φ = {φ : φ = h(θ), θ ∈ Θ} then
 L*[φ, a] = L[h⁻¹(φ), a].
- The decision analysis should be independent of the parametrization.

Equivariant Bayesian Decision Problems

Equivariant Loss Functions

• Consider a loss function for which:

 $L(h(\theta), a) = L(\theta, a)$, for all one-to-one functions $h(\cdot)$.

- Such a loss function is equivariant
- General class of equivariant loss functions: $L(\theta, a) = Q(P_{\theta}, P_{a})$ E.g., Kullback-Leibler divergence loss: $L(\theta, a) = -E[log(\frac{p(x \mid a)}{p(x \mid \theta)}) \mid \theta]$

 $\label{eq:loss} \ensuremath{\mathsf{Loss}} \equiv \ensuremath{\mathsf{probability-weighted}} \ensuremath{\mathsf{log-likelihood}} \ensuremath{\mathsf{ratio}}.$ For canonical exponential family:

$$L(\eta, \mathbf{a}) = \sum_{j=1}^{\kappa} [\eta_j - \mathbf{a}_j) E[T_j(X) \mid \eta] + A(\eta) - A(\mathbf{a})$$

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