## 2.094 — Finite Element Analysis of Solids and Fluids Fall '08 Lecture 20 - Beams, plates, and shells MIT OpenCourseWare

Timoshenko beam theory



The fiber moves up and rotates and its length does not change.

Principle of virtual displacement (Linear Analysis)

$$EI \int_{0}^{L} \left(\overline{\beta}'\right)^{T} \beta' dx + (Ak)G \int_{0}^{L} \left(\frac{d\overline{w}}{dx} - \overline{\beta}\right)^{T} \left(\frac{dw}{dx} - \beta\right) dx = \int_{0}^{L} \overline{w}^{T} p dx$$
(20.1)

Two-node element:



Three-node element:



For a q-node element,

$$\hat{\boldsymbol{u}} = \begin{bmatrix} w_1 & \cdots & w_q & \theta_1 & \cdots & \theta_q \end{bmatrix}^T$$

$$w = \boldsymbol{H}_w \hat{\boldsymbol{u}}$$
(20.2)
(20.3)

$$w = H_w u \tag{20.3}$$
$$\beta = H_\beta \hat{u} \tag{20.4}$$

$$\boldsymbol{H}_w = \begin{bmatrix} h_1 & \cdots & h_q & 0 & \cdots & 0 \end{bmatrix}$$
(20.5)

$$\boldsymbol{H}_{\beta} = \begin{bmatrix} 0 & \cdots & 0 & h_1 & \cdots & h_q \end{bmatrix}$$
(20.6)

$$\boldsymbol{J} = \frac{dx}{dr} \tag{20.7}$$

$$\frac{dw}{dx} = \underbrace{\mathbf{J}^{-1} \mathbf{H}_{w,r}}_{\mathbf{u}} \hat{\mathbf{u}}$$
(20.8)

$$\frac{d\beta}{dx} = \underbrace{J^{-1}H_{\beta,r}}_{B_{\beta}} \hat{u}$$
(20.9)

Hence we obtain

$$\begin{bmatrix} EI \int_{-1}^{1} \boldsymbol{B}_{\beta}^{T} \boldsymbol{B}_{\beta} \det(\boldsymbol{J}) dr + (Ak)G \int_{-1}^{1} \left(\boldsymbol{B}_{w} - \boldsymbol{H}_{\beta}\right)^{T} \left(\boldsymbol{B}_{w} - \boldsymbol{H}_{\beta}\right) \det(\boldsymbol{J}) dr \end{bmatrix} \hat{\boldsymbol{u}}$$
$$= \int_{-1}^{1} \boldsymbol{H}_{w}^{T} p \det(\boldsymbol{J}) dr \quad (20.10)$$
$$\begin{bmatrix} \boldsymbol{K} \hat{\boldsymbol{u}} = \boldsymbol{R} \end{bmatrix}$$
(20.11)

K is a result of the term inside the bracket in (20.10) and R is a result of the right hand side. For the 2-node element,



$$w_1 = \theta_1 = 0 \tag{20.12}$$

$$w_2, \theta_2 = ?$$
 (20.13)

$$\gamma = \frac{w_2}{L} - \frac{1+r}{2}\theta_2 \tag{20.14}$$

We cannot make  $\gamma$  equal to zero for every r (page 404, textbook). Because of this, we need to use about 200 elements to get an error of 10%. (Not good!)

Recall almost or fully incompressible analysis: Principle of virtual displacements:

$$\int_{V} \overline{\boldsymbol{\epsilon}'}^{T} \boldsymbol{C}' \boldsymbol{\epsilon}' dV + \int_{V} \overline{\boldsymbol{\epsilon}}_{v} \left( \kappa \boldsymbol{\epsilon}_{v} \right) dV = \mathcal{R}$$
(20.15)

u/p formulation

$$\int_{V} \overline{\epsilon'}^{T} C' \epsilon' dV - \int_{V} \overline{\epsilon}_{v} p dV = \mathcal{R}$$
(20.16)

$$\int_{V} \overline{p} \left(\frac{p}{\kappa} + \epsilon_{v}\right) dV = 0 \tag{20.17}$$

But now we needed to select wisely the interpolations of u and p. We needed to satisfy the inf-sup condition

$$\underbrace{\inf_{q_h \in \mathbf{Q}_h} \sup_{\boldsymbol{v}_h \in \mathbf{V}_h} \frac{\int_{\mathbf{Vol}} q_h \boldsymbol{\nabla} \cdot \boldsymbol{v}_h d\mathbf{Vol}}{\|q_h\| \|v_h\|} \ge \beta > 0$$
(20.18)

## 4/1 element:



We can show mathematically that this element does not satisfy inf-sup condition. But, we can also show it by giving an example of this element which violates the inf-sup condition.



 $v_1 = \Delta$ ,  $v_2 = 0 \Rightarrow \nabla \cdot v_h$  for both elements is positive and the same. Now, if I choose pressures as above

$$\int_{\text{Vol}} q_h \nabla \boldsymbol{v}_h d\text{Vol} = 0, \quad \text{hence (20.18) is not satisfied!}$$
(20.19)

9/3 element

J



satisfies inf-sup

9/4-c



Getting back to beams

$$EI \int_{0}^{L} \overline{\beta}' \beta dx + (AkG) \int_{0}^{L} \left(\frac{d\overline{w}}{dx} - \overline{\beta}\right) \gamma^{AS} dx = \mathcal{R}$$
(20.20)

$$\int_0^L \bar{\gamma}^{AS} \left(\gamma - \gamma^{AS}\right) dx = 0 \tag{20.21}$$

where

$$\gamma = \frac{dw}{dx} - \beta$$
, from displacement interpolation (20.22)

$$\gamma^{AS} = \text{Assumed shear strain interpolation}$$
 (20.23)

2-node element, constant shear assumption. From (20.21),

$$\int_{0}^{L} \left(\frac{dw}{dx} - \beta\right) \bar{\gamma}^{\mathcal{AS}} dx = \int_{0}^{L} \gamma^{\mathcal{AS}} \bar{\gamma}^{\mathcal{AS}} dx \tag{20.24}$$

$$\Rightarrow -\int_{-1}^{+1} \left(\frac{1+r}{2}\theta_2\right) \cdot \frac{L}{2}dr + w_2 = \gamma^{AS} \cdot L \tag{20.25}$$

$$\Rightarrow \gamma^{AS} = \frac{w_2 - \frac{L}{2}\theta_2}{L} \tag{20.26}$$

θ.

 $\gamma^{AS}$  (shear strain) is equal to the displacement-based shear strain at the middle of the beam.

 $\omega_i = \theta_i = 0$ .

L



Use  $\gamma^{AS}$  in (20.20) to obtain a powerful element. For "our problem",

$$\gamma^{AS} = 0 \quad \text{hence} \quad w_2 = \frac{L}{2}\theta_2 \tag{20.27}$$

$$\Rightarrow EI \int_{0}^{L} \overline{\beta}' \beta' dx = M \,\overline{\beta}\big|_{x=L} \tag{20.28}$$

$$\Rightarrow EI\left(\left(\frac{1}{L}\right)^2 \cdot L\right)\theta_2 = M \tag{20.29}$$

$$\Rightarrow \theta_2 = \frac{ML}{EI}, \qquad w_2 = \frac{ML^2}{2EI}$$
(20.30)

(exact solutions)



Reading: Sec. 4.5.7

## Plates





$$\begin{cases} w = w(x, y) & \text{is the transverse displacement of the mid-surface} \\ v = -z\beta_y(x, y) \\ u = -z\beta_x(x, y) \end{cases}$$
(20.31)

For any particle in the plate with coordinates (x, y, z), the expressions in (20.31) hold! We use

$$w = \sum_{i=1}^{q} h_i w_i \tag{20.32}$$

$$\beta_x = -\sum_{i=1}^q h_i \theta_y^i \tag{20.33}$$

$$\beta_y = +\sum_{i=1}^q h_i \theta_x^i \tag{20.34}$$

where q equals the number of nodes. Then the element locks in the same way as the displacement-based beam element.

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