## **Computational Imaging:** A Survey of Medical and Scientific Applications

**Douglas Lanman\*** 

\* presented by Douglas Lanman, adapted from slides by Marc Levoy: http://graphics.stanford.edu/talks/

## **Computational Imaging in the Sciences**





#### **Driving Factors:**

- new instruments lead to new discoveries (e.g., Leeuwenhoek + microscopy → microbiology)
- Q: most important instrument in last century?
  A: the digital computer

### What is Computational Imagining?

according to B.K.P. Horn:

"...imaging methods in which computation is inherent in image formation."

 digital processing has led to a revolution in medical and scientific data collection

(e.g., CT, MRI, PET, remote sensing, etc.)

## **Computational Imaging in the Sciences**

### **Medical Imaging:**

- transmission tomography (CT)
- reflection tomography (ultrasound)

### **Geophysics:**

- borehole tomography
- seismic reflection surveying

### **Applied Physics:**

- diffuse optical tomography
- diffraction tomography
- scattering and inverse scattering

### **Biology:**

- confocal microscopy
- deconvolution microscopy

#### Astronomy:

- coded-aperture imaging
- interferometric imaging

### **Remote Sensing:**

- multi-perspective panoramas
- synthetic aperture radar

### **Optics:**

- wavefront coding
- light field photography
- holography

# **Medical Imaging**

#### **Overview:**

- (non-invasive) reconstruction of internal structures of living organisms
- generally involves solving an inverse problem
- includes: radiology, endoscopy, thermal imaging, microscopy, etc.

#### **Methods:**

- tomography (includes: CT, MRI, PET, ultrasound)
- electroencephalography (EEG) and magnetoencephalography (MEG)

### **Key Issues:**

- safety (e.g., ionizing radiation)
- minimally invasive
- temporal and spatial resolution
- cost (to a lesser degree)

Two brain MRI images removed due to copyright restrictions.

# What is Tomography?

### **Definition:**

- imaging by sectioning (from Greek tomos: "a section" or "cutting")
- creates a cross-sectional image of an object by transmission or reflection data collected by illuminating from many directions



\* Fig 3.2 and 3.3 in A.C. Kak and M. Slaney, Principles of Computerized Tomographic Imaging, 1988

## Simulated Tomograms



density function

parallel-beam projections (Radon transform)

Rotation Angle fan-beam projections



\* Image: Wikipedia, *Projection-Slice Theorem*, retrieved on 11/03/2008 (public domain); A.C. Kak and M. Slaney, *Principles of Computerized Tomographic Imaging*, 1988

## **Reconstruction: Filtered Backprojection**



Courtesy of A. C. Kak and Malcolm Slaney. Used with permission.

#### **Fourier Projection-Slice Theorem:**

- $F^{-1}{G_{\theta}(\omega)} = P_{\theta}(t)$
- add slices G<sub>θ</sub>(ω) into {u,v} at all angles θ and inverse transform to yield g(x,y)
- add 2D backprojections P<sub>θ</sub>(t) into {x,y} at all angles θ





## Sampling Requirements and Limitations





effect of occlusions



## Medical Applications of Tomography

Video still removed due to copyright restrictions. See Tuttle9955i. "CT at max speed." March 1, 2008. http://www.youtube.com/watch?v=2CWpZKuy-NE

Medical images removed due to copyright restrictions.

Physical phenomenon	Type of tomograph
X-rays	СТ
gamma rays	SPECT
electron-positron annihilation	PET
nuclear magnetic resonance	MRI
ultrasound	ultrasonography
electrons	3D TEM
ions	atom probe

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bone reconstruction segmented vessels

## How to Eliminate Moving Parts?



#### **Prior CT Generations: Time-sequential Projections**

- moving parts
- synchronization and exposure timing
- costs (up-front, operating, and maintenance)
- dynamic scenes (RF interference, switching costs for X-ray tubes)

## How to Eliminate Moving Parts?



#### **Our Solution: Simultaneous Projections**

- no moving parts
- no synchronization  $\rightarrow$  uses "always-on" sources
- lower costs (simpler mechanical construction and X-ray sources)
- well-suited for high-speed capture of dynamic scenes

## **Shield Fields:**

### Simultaneous Projections using Attenuating Masks





allows spatial heterodyning

## **Shield Fields:**

Simultaneous Projections using Attenuating Masks





# **Geophysical Applications**

Two diagrams removed due to copyright restrictions. Borehole tomography and map of seismosaurus. From Reynolds, J.M., *An Introduction to Applied and Environmental Geophysics.* Wiley, 1997.

> mapping a *seismosaurus* in sandstone using microphones in 4 boreholes and explosions along radial lines

#### **Borehole Tomography:**

- receivers measure end-to-end travel time
- reconstruct to find velocities in intervening cells
- must use limited-angle reconstruction methods (e.g., ART)

# **Geophysical Applications**

Diagram removed due to copyright restrictions. Borehole tomography. From Reynolds, J.M., *An Introduction to Applied and Environmental Geophysics.* Wiley, 1997.

Photo removed due to copyright restrictions. Stone map fragment from Stanford Forma Urbis Romae Project. http://formaurbis.stanford.edu/fragments/color\_mos\_red uced/010g\_MOS.jpg

mapping ancient Rome using explosions in the subways and microphones along the streets?

#### **Borehole Tomography:**

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# **Optical Diffraction Tomography (ODT)**



weakly-refractive media using coherent plane-wave illumination

- the amplitude and phase of the forward-scattered field can be described using the Fourier Diffraction Theorem, such that: F {scattered field} = arc in F{object}
- repeat for multiple wavelength, use F<sup>-1</sup> to reconstruct volume
- broadband hologram will yield 3D structure (i.e., refraction indices)

Figures from A.C. Kak and M. Slaney, Principles of Computerized Tomographic Imaging, 1988

Objects

k=17k.

k=6k

Objects

k,

k=2k

k = 3kk = 4k = 51

# **Optical Diffraction Tomography (ODT)**





#### synthetic ODT reconstruction example

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Courtesy of A. C. Kak and Malcolm Slaney. Used with permission.

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# **Optical Diffraction Tomography (ODT)**

Diagram removed due to copyright restrictions. Source: Jebali, Asma. "Numerical Reconstruction of semi-transparent objects in Optical Diffraction Tomography." Diploma Project, Ecole Polytechnique, Lausanne, 2002.



synthetic ODT reconstruction example

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- backprojection possible using a depth-variant filter

## Diffuse Optical Tomography (DOI/DOT)







mammography application: sources (red), detectors (blue) absorption (yellow is high)

Scattering (yellow is high)



- strongly-refractive media using inverse-scattering
- assumes propagation due to multiple scattering
- models transport as a diffusion process
- inversion is non-linear and ill-posed (i.e., hard)
- example: 81 emitters and 81 receivers, where time-of-flight gives initial estimate for absorption

Images: Schweiger, M., et al. "Computational Aspects of Diffuse Optical Tomography." *IEEE Computing in Science and Engineering* 5, no. 6 (November/December 2003): 33-41. © 2003 IEEE. Courtesy of IEEE. Used with permission.

## Diffuse Optical Tomography (DOI/DOT)

Images removed due to copyright restrictions. See Figure 4 in Gibson, A. P., et al. "Recent Advances in diffuse optical imaging." *Physics in Medicine and Biology* 50, no. 4 (2005): R1. <u>http://www.medphys.ucl.ac.uk/research/borl/pdf/gibson\_pmb\_2005.pdf</u>

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## **Electrical Impedance Tomography**



Kerrouche, N. et al. Physiol. Meas. 22 No 1 (February 2001) 147-157

electrode array (wires attached) reconstructed conductivity map

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chest electrode array

- strongly-refractive media using inverse-scattering
- assumes propagation due to multiple scattering
- models transport as a diffusion process
- inversion is non-linear and ill-posed (i.e., hard)
- EIT: inverse problem called "Calderón Problem"

Image: Schweiger, M., et al. "Computational Aspects of Diffuse Optical Tomography." *IEEE* Computing in Science and Engineering 5, no. 6 (November/December 2003): 33-41. © 2003 IEEE. Courtesy of IEEE. Used with permission.

# **Biology: 3D Deconvolution**



### focal stack of a point in 3D is the 3D PSF of the imaging system

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#### **Basics of 3D Deconvolution for Microscopy:**

- object \* PSF  $\rightarrow$  focal stack
- $F{object} \times F{PSF} \rightarrow F{focal stack}$
- $F{\text{focal stack}} \div F{\text{PSF}} \rightarrow F{\text{object}}$
- spectrum contains zeros (due to missing rays)
- imaging noise is amplified by division by ~zeros
- reduce by regularization (smoothing) or completion of spectrum
- improve convergence using constraints, e.g. object > 0 (positivity)

#### \* Slide derived from Marc Levoy

# **Biology: 3D Deconvolution**

slice of focal stack



slice of volume



volume rendering



#### **3D Deconvolution Microscopy:**

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- $F{object} \times F{PSF} \rightarrow F{focal stack}$
- $F{\text{focal stack}} \div F{\text{PSF}} \rightarrow F{\text{object}}$





\* Slide derived from Marc Levoy

\* first patented by Marvin Minsky in 1957







# **Confocal Microscopy Examples**



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Several confocal microscopy images removed due to copyright restrictions.



Diagrams removed due to copyright restrictions. Process for capturing and recontructing a coded aperture image; schematic of a shielded detector.



- cannot practically focus X-rays using optics
- pinhole would work, but requires long exposures
- instead, use multiple pinholes and a single sensor
- produces superimposed shifted copies of source



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Images removed due to copyright restrictions. See <a href="http://www.paulcarlisle.net/codedaperture">http://www.paulcarlisle.net/codedaperture</a>

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- MURA: Modified Uniformly Redundant Array (key property: 50% open, autocorrelation function is a delta function)



Images removed due to copyright restrictions. See <a href="http://www.paulcarlisle.net/codedaperture">http://www.paulcarlisle.net/codedaperture</a>

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# Near-Field Coded Aperture Imaging

Diagrams removed due to copyright restrictions. Process for capturing and recontructing a coded aperture image; schematic of a shielded detector.

Diagram removed due to copyright restrictions. Schematic of flux passing through mask into detector.

#### **Coded Aperture Imaging (Source Reconstruction):**

- backproject each detected pixel intensity through each hole in mask
- superimposition of projections reconstructs source (plus a bias)
- essentially a cross-correlation of detected image with mask
- also works for non-infinite sources (in which case, must use voxel grid)
- assumes sources are not occluded (except by the mask)

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