## Key Points: Derivatives

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#### **Discrete Models**

- Definitions of SPD ( $\pi$ ) and risk-neutral probability (**Q**).
- Absence of arbitrage is equivalent to existence of the SPD or a risk-neutral probability:

$$P_t = \mathsf{E}_t^{\mathbf{P}} \left[ \sum_{u=t+1}^T \frac{\pi_u}{\pi_t} D_u \right] = \mathsf{E}_t^{\mathbf{Q}} \left[ \sum_{u=t+1}^T \frac{B_t}{B_u} D_u \right]$$

• Price of risk: under Gaussian P and Q distributions,

$$\varepsilon_t^{\mathbf{Q}} = \varepsilon_t^{\mathbf{P}} + \eta_t$$

Log-normal model (discrete version of Black-Scholes):

$$\mu_t - r_t = \sigma_t \eta_t$$

#### **Stochastic Calculus**

- Brownian motion, basic properties (IID Gaussian increments, continuous trajectories, nowhere differentiable).
- Quadratic variation.  $[Z]_T = T$ . Heuristically,

$$(dZ_t)^2 = dt$$

- Stochastic integral.
- Ito's lemma:

$$df(t, X_t) = \frac{\partial f(t, X_t)}{\partial t} dt + \frac{\partial f(t, X_t)}{\partial X_t} dX_t + \frac{1}{2} \frac{\partial^2 f(t, X_t)}{\partial X_t^2} (dX_t)^2$$

Multivariate Ito's lemma.

$$df(t, X_t, Y_t) = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial X_t} dX_t + \frac{\partial f}{\partial Y_t} dY_t + \frac{1}{2} \frac{\partial^2 f}{\partial X_t^2} (dX_t)^2 + \frac{1}{2} \frac{\partial^2 f}{\partial Y_t^2} (dY_t)^2 + \frac{\partial^2 f}{\partial X_t \partial Y_t} dX_t dY_t$$

- Arbitrage-free pricing of options by replication.
- European option with payoff  $H(S_T)$ .
- Replicating portfolio delta is

$$\theta_{t} = \frac{\partial f(t, S_{t})}{\partial S_{t}}$$
$$-r f(t, S) + \frac{\partial f(t, S)}{\partial t} + rS \frac{\partial f(t, S)}{\partial S} + \frac{1}{2}\sigma^{2}S^{2} \frac{\partial^{2} f(t, S)}{\partial S^{2}} = 0$$
with the boundary condition  $f(T, S) = H(S)$ .

# Pricing by Replication: Limitations

- In many models cannot derive a unique price for a derivative.
- Term structure models, stochastic volatility.
- Price assets relative to each other. Replication argument combined with assumptions on prices of risk.
- Alternatively, specify dynamics directly under Q.

#### **Risk-Neutral Pricing**

General pricing formula

$$P_t = \mathsf{E}_t^{\mathbf{Q}} \left[ \exp\left( - \int_t^T r_s \, ds \right) H_T \right]$$

- Need to specify dynamics of the underlying under Q.
- If underlying is a stock, only one way to do this: set expected return to r.
- Q dynamics is related to P through price of risk

$$dZ_t^{\mathbf{P}} = -\eta_t \, dt + dZ_t^{\mathbf{Q}}$$

Risk premium

$$\mathsf{E}_{t}^{\mathsf{P}}\left[\frac{dS_{t}}{S_{t}}\right] - r_{t} dt = \mathsf{E}_{t}^{\mathsf{P}}\left[\frac{dS_{t}}{S_{t}}\right] - \mathsf{E}_{t}^{\mathsf{Q}}\left[\frac{dS_{t}}{S_{t}}\right]$$

### **Risk-Neutral Pricing and PDEs**

- Derive a PDE on derivative prices using Ito's lemma.
- One-factor term structure model

$$\mathsf{E}_t[df(t, r_t)] = r_t f(t, r_t) \, dt$$

Vasicek model:

$$dr_t = -\kappa(r_t - \overline{r}) dt + \sigma dZ_t^{\mathbf{Q}}$$

•  $f(t, r_t)$  must satisfy the PDE

$$\frac{\partial f(t,r)}{\partial t} - \kappa(r-\overline{r})\frac{\partial f(t,r)}{\partial r} + \frac{1}{2}\sigma^2\frac{\partial^2 f(t,r)}{\partial r^2} = rf(t,r)$$

with the boundary condition

$$f(T, r) = 1$$

Expected bond returns satisfy

$$\mathsf{E}_t\left(\frac{dP(t,T)}{P(t,T)}\right) = (r_t + \sigma_t^P \eta_t) \, dt$$

## Monte Carlo Simulation

- Random number generation: inverse transform, acceptance-rejection method.
- Variance reduction: antithetic variates, control variates.
- Intuition behind control variates: carve out the part of the estimated moment that is known in closed form, no need to estimate that by Monte Carlo.
- Good control variates: highly correlated with the variable of interest, expectation known in closed form.
- Examples of control variates: stock price, payoff of similar option, etc.

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